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FIXED POINT THEORY FOR SIMULATION FUNCTIONS IN G-METRIC SPACES: A NOVEL APPROACH

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Abstract: In this paper, with the aid of simulation mapping $\eta : [0, \infty) \times [0, \infty) \to \mathbb{R}$, we prove some Lemmas and fixed point result for generalized Z – contraction of the mapping $g : X \to X$ satisfying the following conditions: $\eta(g(gx, gy, gz), \mathcal{M}(x, y, z)) \ge 0$,

for all $x, y, z \in X$, where

 $\mathcal{M}(x,y,z) = \max \{ \mathcal{G}(x,gy,gy), \mathcal{G}(y,gx,gx), \mathcal{G}(y,gz,gz), \mathcal{G}(z,gy,gy), \mathcal{G}(z,gx,gx), \mathcal{G}(x,gz,gz) \}.$

and (X, G) is a G – metric space. An example is also given to support our results.

Keywords: fixed point; generalized Z – contraction; simulation function; G – metric spaces.

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1. INTRODUCTION

A metric space is a nonempty set X with a two-variable map d that allows us to calculate the distance between two points. We must find the distance not just between integers and vectors,

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but also between sequences and functions in higher mathematics. Numerous approaches exist in this sector in order to discover a suitable concept of a metric space. Many renowned mathematicians have considered various generalizations of a metric space. Mustafa and Sims [1] presented G –metric space in 2006 and provided an essential generalization of a metric space as follows:

Definition 1.1. [1] Let X be a non empty set and $G: X^3 \rightarrow [0, \infty)$ be a map which satisfies the following properties:

- 1. G(x, y, z) = 0 if x = y = z,
- 2. 0 < G(x, x, y) whenever $x \neq y$,
- 3. $G(x, x, y) \leq G(x, y, z), y \neq z$,
- 4. G(x, y, z) = G(x, z, y) = G(y, x, z) = G(z, x, y) = G(y, z, x) = G(z, y, x),
- 5. $G(x, y, z) \leq G(x, a, a) + G(a, y, z), \forall x, y, z, a \in X.$

Then, the function G is said to be G – metric on X and the pair (X, G) is known as G – metric space.

Banach [2] established the Banach contraction principle, a useful conclusion in fixed point theory involving a contraction mapping, in 1922.

Definition 1.2. [2] Let (X, d) be a complete metric space and let $f : X \to X$ be a self-mapping. Let d(fx, fy) < d(x, y) holds for all $x, y \in X$ with $x \neq y$. Then, f is called a contraction known as Banach contraction.

Following this approach, a number of scholars expanded on it by offering various contractions on metric spaces [3, 4-9]. We introduce a mapping, namely the simulation function, and the concept of generalized Z – contraction in this paper. Khojasteh et al. [10] have proposed a new class of mappings known as simulation functions. Later, Argoubi et al. [11] made a minor change to the definition of simulation functions by removing a constraint.

Definition 1.3. [11] A simulation function is a mapping $\zeta : [0, \infty) \times [0, \infty) \rightarrow \mathbb{R}$ satisfying the following conditions:

 $(\zeta_1) \zeta(t,s) < s - t$ for all t, s > 0

 (ζ_2) if $\{t_n\}$ and $\{s_n\}$ are sequences in $(0,\infty)$ such that

$$\lim_{n \to \infty} \{t_n\} = \lim_{n \to \infty} \{s_n\} = l \in (0, \infty),$$

then

$$\lim_{n\to\infty}\sup\zeta(t_n,s_n) < 0$$

2. MAIN RESULTS

In this section, we prove certain Lemmas and some fixed point results for generalized Z – contraction in G – metric space.

Definition 2.1. Let (X, \mathcal{G}) be a \mathcal{G} - metric space, $g : X \to X$ a mapping and $\eta \in \mathbb{Z}$. Then g is called a generalized \mathbb{Z} - contraction with respect to η if the following condition is satisfied

$$\eta(\mathcal{G}(gx, gy, gz), \mathcal{M}(x, y, z)) \ge 0, \tag{1}$$

for all $x, y, z \in X$, where $\mathcal{M}(x, y, z) =$

 $\max \{ \mathcal{G}(x, gy, gy), \mathcal{G}(y, gx, gx), \mathcal{G}(y, gz, gz), \mathcal{G}(z, gy, gy), \mathcal{G}(z, gx, gx), \mathcal{G}(x, gz, gz) \}.$

Lemma 2.2. Let (X, \mathcal{G}) denote a \mathcal{G} - metric space and $g : X \to X$ denote a generalized Z - contraction with regard to \mathbb{Z} . Then, for all $x \in X, g$ is asymptotically regular.

Proof: Let $x \in X$ be arbitrary. If for some $k \in \mathbb{N}$, $g^k x = g^{k-1}x$, then $g^{k-1}x$ is a fixed point of g. Therefore, we have

$$\begin{aligned} \mathcal{G}(g^{n}x, g^{n+1}x, g^{n+1}x) &= \mathcal{G}(g^{n-k+1}g^{k-1}x, g^{n-k+2}g^{k-1}x, g^{n-k+2}g^{k-1}x) \\ &= \mathcal{G}(g^{n-k+1}y, g^{n-k+2}y, g^{n-k+2}y) \\ &= \mathcal{G}(y, y, y) = 0. \end{aligned}$$

Therefore, $\lim_{n\to\infty} \mathcal{G}(g^n x, g^{n+1} x, g^{n+1} x) = 0.$

So, let us suppose that $g^n x \neq g^{n-1}x$ for all $n \in \mathbb{N}$, then it follows from (1) that $\eta(\mathcal{G}(g^{n+1}x, g^n x, g^n x), \mathcal{M}(g^n x, g^{n-1}x, g^{n-1}x)) \ge 0,$

since g is a generalized contraction, where

$$\mathcal{M}(g^{n}x, g^{n-1}x, g^{n-1}x) = \max \{ \mathcal{G}(g^{n}x, g^{n}x, g^{n}x), \mathcal{G}(g^{n-1}x, g^{n+1}x, g^{n+1}x), \\ \mathcal{G}(g^{n-1}x, g^{n+1}x, g^{n+1}x), \mathcal{G}(g^{n-1}x, g^{n}x, g^{n}x), \\ \mathcal{G}(g^{n-1}x, g^{n+1}x, g^{n+1}x), \mathcal{G}(g^{n-1}x, g^{n}x, g^{n}x), \\ \mathcal{G}(g^{n-1}x, g^{n+1}x, g^{n+1}x), \mathcal{G}(g^{n-1}x, g^{n}x, g^{n}x), \\ \mathcal{G}(g^{n-1}x, g^{n+1}x), \\ \mathcal{G}(g^{n-1}x, g^{n}x), \\ \mathcal{G}(g^{n-1}x, g^{n+1}x), \\ \mathcal{G}(g^{n-1}x, g^{n}x), \\ \mathcal{G}(g^{n-1}x, g^{n+1}x), \\ \mathcal{G}(g^{n-1}x, g^{n}x), \\ \mathcal{G}(g^{n-1}x, g^{n+1}x), \\ \mathcal{G}(g^{n-1}x$$

$$\begin{split} \mathcal{G}(g^{n-1}x,g^nx,g^nx), \mathcal{G}(g^{n-1}x,g^{n+1}x,g^{n+1}x), \\ \mathcal{G}(g^nx,g^nx,g^nx) \} \\ &= \max\{\mathcal{G}(g^nx,g^{n-1}x,g^{n-1}x), \mathcal{G}(g^{n+1}x,g^nx,g^nx)\}, \text{ since } \\ \mathcal{G}(g^{n+1}x,g^{n-1}x,g^{n-1}x) &\leq \mathcal{G}(g^{n+1}x,g^nx,g^nx) + \mathcal{G}(g^nx,g^{n-1}x,g^{n-1}x). \\ \text{If } \max\{\mathcal{G}(g^nx,g^{n-1}x,g^{n-1}x), \mathcal{G}(g^{n+1}x,g^nx,g^nx)\} = \mathcal{G}((g^{n+1}x,g^nx,g^nx), \text{ then } \\ \eta\big(\mathcal{G}(g^{n+1}x,g^nx,g^nx), \mathcal{M}(g^nx,g^{n-1}x,g^{n-1}x)\big) \\ &= \eta(\mathcal{G}(g^{n+1}x,g^nx,g^nx), \mathcal{G}(g^{n+1}x,g^nx,g^nx,g^nx)) \geq 0, \end{split}$$

which is a contradiction. So, $\mathcal{G}(g^{n+1}x, g^n x, g^n x) < \mathcal{G}(g^n x, g^{n-1}x, g^{n-1}x)$ holds. This shows that $\mathcal{G}(g^n x, g^{n-1}x, g^{n-1}x)$ is monotonically decreasing sequence of non-negative reals and so it must be convergent.

Let $\lim_{n\to\infty} \mathcal{G}(g^n x, g^{n-1} x, g^{n-1} x) = s.$

If s > 0, then by contraction condition

$$0 \le \lim_{n \to \infty} \sup \eta \left(\mathcal{G}(g^{n+1}x, g^n x, g^n x), M(g^n x, g^{n-1}x, g^{n-1}x) \right)$$

=
$$\lim_{n \to \infty} \sup \eta \left(\mathcal{G}(g^{n+1}x, g^n x, g^n x), M(g^n x, g^{n-1}x, g^{n-1}x) \right) < 0,$$

a contradiction and thus s > 0 and g is asymptotically regular.

Lemma 2.3. Every Picard sequence converges to its unique fixed point, which is found in every generalized Z – contraction mapping on a complete G – metric space where $x_n = gx_{n-1}$ for all $n \in \mathbb{N}$.

Proof: Let (X, \mathcal{G}) denote a \mathcal{G} - metric space and $g : X \to X$ a mapping and $\zeta \in \mathbb{Z}$.

Let us first demonstrate that if g has a fixed point, it is unique.

If the mapping g has two fixed points $p, r \in X$, then d(p, r) > 0.

By (1), we get

$$\eta(\mathcal{G}(gp, gr, gr), \mathcal{M}(p, r, r)) > 0,$$

where

 $\mathcal{M}(p,r,r)$ = max{ $\mathcal{G}(p,gr,gr), \mathcal{G}(r,gp,gp), \mathcal{G}(r,gr,gr), \mathcal{G}(r,gr,gr), \mathcal{G}(p,gr,gr), \mathcal{G}(p,gr,gr)$ } = $\mathcal{G}(p,r,r)$, which contradicts(ζ_2). As a result, there is just one fixed point.

Now, we shall show that if $\{x_n\}$ is a Picard sequence created by g then $\lim_{n\to\infty} x_n = z$ is only fixed point.

Let $x_0 \in X$ be any number, and $\{x_n\}$ be the Picard sequence, with $x_n = g$ for all $n \in \mathbb{N}$. Assume, on the other hand, that $\{x_n\}$ is not bounded. We can assume that $x_{n+k} \neq x_n$ for any $n, k \in \mathbb{N}$ without losing generality. Because $\{x_n\}$ is unbounded, there is a subsequence $\{x_{n_k}\}$ such that $n_1 = 1$ and for each $k \in \mathbb{N}$, n_{k+1} is the smallest integer.

$$G(x_{n_{k+1}}, x_{n_k}, x_{n_k}) > 1$$
 and

$$G(x_m, x_{n_k}, x_{n_k}) \le 1$$
 for $n_k \le m \le n_{k+1} - 1$

Therefore, by triangle inequality, we have

$$1 < \mathcal{G}(x_{n_{k+1}}, x_{n_k}, x_{n_k})$$

$$\leq \mathcal{G}(x_{n_{k+1}}, x_{n_{k+1}} - 1, x_{n_{k+1}} - 1) + \mathcal{G}(x_{n_{k+1}} - 1, x_{n_k}, x_{n_k})$$

$$\leq \mathcal{G}(x_{n_{k+1}}, x_{n_{k+1}} - 1, x_{n_{k+1}} - 1) + 1.$$

Letting $k \to \infty$ and using Lemma 2.2, we get

$$\lim_{k\to\infty}\mathcal{G}(x_{n_{k+1}},x_{n_k},x_{n_k}) = 1,$$

$$\mathcal{M}(x_{n_{k+1}} - 1, x_{n_{k-1}} - 1, x_{n_{k-1}} - 1)$$

$$= \max \{ \mathcal{G}(x_{n_{k+1}} - 1, gx_{n_{k-1}} - 1, gx_{n_{k+1}} - 1), \mathcal{G}(x_{n_{k-1}} - 1, x_{n_{k+1}} - 1, x_{n_{k+1}} - 1), g(x_{n_{k-1}} - 1, x_{n_{k-1}} - 1, x_{n_{k-1}} - 1), g(x_{n_{k-1}} - 1, x_{n_{k-1}} - 1), g(x_{n_{k-1}} - 1, x_{n_{k-1}} - 1), g(x_{n_{k-1}} - 1, gx_{n_{k-1}} - 1), g(x_{n_{k-1}} - 1), g(x_{n_{k-1}} - 1, gx_{n_{k-1}} - 1), g(x_{n_{k-1}} - 1), g(x_{n_{k-1}} - 1, gx_{n_{k-1}} - 1), g(x_{n_{k-1}} - 1), g(x_$$

Now, since g is a generalized Z – contraction, so that

$$0 \leq \lim_{k \to \infty} \sup \eta \left(\mathcal{G} \left(g x_{n_{k+1}} - 1, g x_{n_{k-1}} - 1, g x_{n_{k+1}} - 1 \right) \right)$$
$$= \lim_{k \to \infty} \sup \eta \left(\mathcal{G} \left(x_{n_{k+1}}, x_{n_k}, x_{n_k} \right), \mathcal{G} \left(x_{n_{k+1}} - 1, x_{n_{k-1}}, x_{n_{k-1}} \right) \right) < 0,$$

a contradiction. This contradiction proves the result.

Theorem 2.4. Let (X, \mathcal{G}) be a complete \mathcal{G} – metric space and $g : X \to X$ a mapping and $\eta \in \mathbb{Z}$ and this is ageneralized \mathbb{Z} – contraction. Then, g has a unique fixed point u in X and for every $x_0 \in X$ the Picard sequence $\{x_n\}$, where $x_n = gx_{n-1}$ for all $\in \mathbb{N}$ converges to the fixed point of g.

Proof: Let $x_0 \in X$ be arbitrary and $\{x_n\}$ be the Picard sequence, i.e. $x_n = gx_{n-1} \forall n \in \mathbb{N}$. We shall show that this sequence is a Cauchy sequence.

For this, let

$$C_n = \sup\{x_p, x_r, x_r: p, r \ge n\}.$$

Note that the sequence $\{x_n\}$ is monotonically decreasing sequence of the reals and by Lemma 2.3, the sequence $\{x_n\}$ is bounded, therefore $C_n < \infty$ for all $n \in \mathbb{N}$. Thus, $\{C_n\}$ is monotonic bounded sequence, therefore converges, that is $\exists C \ge 0$ such that $C_n = C$. We shall show that C = 0. If C > 0, then by the definition of C_n , for every $k \in \mathbb{N}$, $\exists m_k > n_k \ge k$ and $C_k - \frac{1}{k} < \mathcal{G}(x_{m_k}, x_{n_k}, x_{n_k}) \le C_k$.

Hence,

$$\lim_{k \to \infty} \mathcal{G}(x_{m_k}, x_{n_k}, x_{n_k}) \le C_k \tag{2}$$

Using (1) and the triangular inequality, we obtain

$$\begin{aligned} \mathcal{G}(x_{m_k}, x_{n_k}, x_{n_k}) &\leq \mathcal{G}(x_{m_{k-1}}, x_{n_{k-1}}, x_{n_{k-1}}) \\ &\leq \mathcal{G}(x_{m_{k-1}}, x_{m_k}, x_{m_k}) + \mathcal{G}(x_{m_k}, x_{n_k}, x_{n_k}) + \mathcal{G}(x_{n_k}, x_{n_{k-1}}, x_{n_{k-1}}). \\ \mathcal{G}(x_{m_{k-1}}, x_{m_k}, x_{m_k}) \to 0, \ \mathcal{G}(x_{n_k}, x_{n_{k-1}}, x_{n_{k-1}}) \to 0 \ \text{as} \ k \to \infty. \end{aligned}$$

Then, by Squeeze Theorem, we have

We know that $\mathcal{G}(x_{m_{k-1}}, gx_{n_{k-1}}, gx_{n_{k-1}}) = C$ as well

$$\mathcal{M}(x_{m_{k-1}}, x_{n_{k-1}}, x_{n_{k-1}}) \to 0, \mathcal{G}(x_{n_k}, x_{n_{k-1}}, x_{n_{k-1}}) \to 0 \text{ as } k \to \infty,$$
$$0 \le \lim_{k \to \infty} \sup \eta \left(\mathcal{G}(x_{m_k}, x_{n_k}, x_{n_k}), \mathcal{M}(x_{m_{k-1}}, x_{n_{k-1}}, x_{n_{k-1}}) < 0.$$

This contradiction proves that C = 0 and so $\{x_n\}$ is a Cauchy sequence. Since X is a complete \mathcal{G} – metric space, $\exists u \in X$ such that $\lim_{n \to \infty} x_n = u$. We shall show that the point u is a fixed point of g. Suppose $gu \neq u$, then $\mathcal{G}(u, gu, gu) > 0$. Again, using (1), we have

$$0 \le \lim_{k \to \infty} \sup \eta \left(\mathcal{G} \left(x_{m_k}, x_{n_k}, x_{n_k} \right), \mathcal{M} \left(x_{m_{k-1}}, x_{n_{k-1}}, x_{n_{k-1}} \right) \right) < 0.$$

$$\lim_{n \to \infty} \mathcal{G} (gz, gx_n, gx_n) = \lim_{n \to \infty} \mathcal{G} (gz, gx_{n+1}, gx_{n+1}) = \mathcal{G} (gz, z, z) > 0$$

and

$$\mathcal{M}(z, x_n, x_n) = \max \{ \mathcal{G}(gz, gx_n, gx_n), \mathcal{G}(x_n, gz, gz), \mathcal{G}(x_n, gx_n, gx_n), \mathcal{G}(x_n, gx_n, gx_n), \mathcal{G}(x_n, gz, gz), \mathcal{G}(z, gx_n, gx_n) \}.$$

Therefore, $\mathcal{M}(z, x_n, x_n) \to \mathcal{G}(gz, z, z)$ as $n \to \infty$.

By contractive condition,

$$0 \le \eta(\mathcal{G}(gz, gx_n, gx_n), \mathcal{M}(z, x_n, x_n)) \to \eta(\mathcal{G}(gz, z, z), \mathcal{M}(gz, z, z)) \text{ as } n \to \infty.$$

By (ζ_2) , we have $\eta(\mathcal{G}(gz, z, z), \mathcal{M}(gz, z, z)) < 0$ which contradicts the contraction condition.

That means gz = z and z is the unique fixed point of g.

Example 2.5. Let X = [0, 1] and $g : X \to X \to \mathbb{R}$ be defined by

$$\mathcal{G}(x, y, z) = max\{|x - y|, |y - z|, |z - x|\}.$$

Then (X, \mathcal{G}) is a complete \mathcal{G} -Metric space.

Define a mapping $g: X \to X$ as $gx = \frac{x}{x+1}$ for all $x \in X$. g is a continuous function but it is not a Banach contraction. But it is a generalized Z – contraction with respect to $\eta \in Z$, where

$$\eta(t,s) = \frac{s}{s+1} - t \text{ for all } t,s \in [0,\infty).$$

Indeed, if $x, y \in X$, then by a simple calculation it can be shown that $\eta(\mathcal{G}(gx, gy, gz), \mathcal{M}(x, y, z)) \ge 0$ for all $x, y \in X$,

where

 $\mathcal{M}(x, y, z) = \max \{ \mathcal{G}(x, gy, gy), \mathcal{G}(y, gx, gx), \mathcal{G}(y, gz, gz), \mathcal{G}(z, gy, gy), \mathcal{G}(z, gx, gx), \mathcal{G}(x, gz, gz) \}.$

Clearly, 0 is the fixed point of g.

CONFLICT OF INTERESTS

The authors declare that there is no conflict of interests.

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