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# COMMON FIXED-POINT THEOREM IN TRIANGULAR INTUITIONISTIC FUZZY METRIC SPACES 

SHRUTI EKTARE*, AMIT KUMAR PANDEY<br>Department of Mathematics, Sarvepalli Radhakrishnan University, Bhopal, P.O. Box 462047, Madhya Pradesh, India

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#### Abstract

The goal of this paper is to prove a new general common fixed-point theorem for two pairs of mappings under different conditions, based on the idea of weakly compatible mappings satisfying a general class of contractions defined by an implicit relation in the framework of triangular intuitionistic fuzzy metric space, which unifies, extends, and generalises most of the existing relevant common fixed-point theorems in the literature. There are also some related results and an illustrated case to demonstrate the realised improvements.


Keywords: triangular intuitionistic fuzzy metric space; common fixed point; implicit relation; weakly compatible mappings; contractions.

2010 AMS Subject Classification: 47 H 10 .

## 1. Introduction and Preliminaries

In 1965, Zadeh [45] proposed the concept of a fuzzy set. Kramosil and Michalek [23] proposed the fuzzy metric space concept in 1975, which can be thought of as a generalisation of the statistical (probabilistic) metric space. This work laid a solid foundation for the development of

[^0]fixed-point theory in fuzzy metric spaces. Grabiec [9] then defined the completeness of the fuzzy metric space (now called a G-complete fuzzy metric space) and extended the Banach contraction theorem to G-complete fuzzy metric spaces. Successively, George and Veeramani [7] modified the definition of the Cauchy sequence introduced by Grabiec. Meanwhile, George and Veeramani [7] somewhat modified Kramosil and Michalek's idea of a fuzzy metric space and constructed a Hausdorff and first countable topology on it. Since then, George and Veeramani's concept of a full fuzzy metric space has arisen as alternative characterisation of completeness, and various fixed-point theorems have been proved using this metric space. We can see from the above analysis that there are numerous studies connected to fixed-point theory based on the two types of complete fuzzy metric spaces mentioned above (see for more details [3-4, 7-9, 40, 43-45] and the references therein). He showed that, for each intuitionistic fuzzy metric space $(X, M, N, *, \diamond)$, the topology generated by the intuitionistic fuzzy metric $(M, N)$ coincides with the topology generated by the fuzzy metric $M$. For more details on intuitionistic fuzzy metric space and related results we refer the reader to $[1,12,17,25-29,32,36]$.

Throughout this paper $\mathbb{R}$ and $\mathbb{R}_{+}$will represents the set of real numbers and nonnegative real numbers, respectively.

The following two definitions are required in the sequel which can be found in [38].
Definition 1.1 A binary operation $*:[0,1] \times[0,1] \rightarrow[0,1]$ is continuous $t$-norm if $*$ satisfying the following conditions:
(1). $*$ is commutative and associative;
(2). $*$ is continuous;
(3). $a * 1=a, \forall a \in[0,1]$;
(4). $a * b \leq c * d$ whenever $a \leq c$ and $b \leq d, \forall a \in[0,1]$.

Definition 1.2 A binary operation $\diamond:[0,1] \times[0,1] \rightarrow[0,1]$ is continuous $t$-conorm if $\diamond$ satisfying the following conditions:
(1). $\diamond$ is commutative and associative;
(2). $\odot$ is continuous;
(3). $a \diamond 0=a, \forall a \in[0,1]$;
(4). $a \diamond b \leq c \diamond d$ whenever $a \leq c$ and $b \leq d, \forall a \in[0,1]$.

In 2004, Park [31] introduced the concept of intuitionistic fuzzy metric space as follows.
Definition 1.3 A 5-tuple $(X, M, N, *, \diamond)$ is said to be an intuitionistic fuzzy metric space if X is an arbitrary set, $*$ is a continuous t -norm, $\diamond$ is a continuous t-conorm, and $M, N$ are two fuzzy sets on $X^{2} \times(0, \infty)$ satisfying the following conditions, for all $\xi, \eta, \sigma \in X$ and $s, t>0$ :
(IFMS1). $M(\xi, \eta, t)+N(\xi, \eta, t) \leq 1 ;$
(IFMS2). $M(\xi, \eta, t)>0$;
(IFMS3). $M(\xi, \eta, t)=1$ for all $t>0 \Leftrightarrow \xi=\eta$;
(IFMS4). $M(\xi, \eta, t)=M(\eta, \xi, t) ;$
(IFMS5). $M(\xi, \eta, t) * M(\eta, \sigma, s) \leq M(\xi, \sigma, t+s) ;$
(IFMS6). $M(\xi, \eta,):.(0, \infty) \rightarrow[0,1]$ is left continuous;
(IFMS7). $\lim _{t \rightarrow \infty} M(\xi, \eta, t)=1$;
(IFMS8). $N(\xi, \eta, t)>0$;
(IFMS9). $N(\xi, \eta, t)=0$ for all $t>0 \Leftrightarrow \xi=\eta$;
(IFMS10). $N(\xi, \eta, t)=N(\eta, \xi, t) ;$
(IFMS11). $N(\xi, \eta, t) \diamond N(\eta, \sigma, s) \geq N(\xi, \sigma, t+s) ;$
(IFMS12). $N(\xi, \eta,):.(0, \infty) \rightarrow[0,1]$ is right continuous;
(IFMS13). $\lim _{t \rightarrow \infty} N(\xi, \eta, t)=0$;
Then $(M, N)$ is called an intuitionistic fuzzy metric space on $X$. The functions $M(\xi, \eta, t)$ and $N(\xi, \eta, t)$ denote the degree of nearness and the degree on nonnearness between x and y with respect to $t$, respectively.

Definition 1.4 (see [31]) Let $(X, M, N, *, \diamond)$ be an intuitionistic fuzzy metric space. Then:
(1). A sequence $\left\{\xi_{n}\right\}$ is said to be Cauchy sequence whenever for all $t>0$,

$$
\lim _{m, n \rightarrow \infty} M\left(\xi_{n}, \xi_{m}, t\right)=1 \text { and } \lim _{m, n \rightarrow \infty} N\left(\xi_{n}, \xi_{m}, t\right)=0
$$

That is, for each $\varepsilon>0$ and $t>0$, there exists a natural number $n_{0}$ such that for all $n, m \geq n_{0}$,

$$
M\left(\xi_{n}, \xi_{m}, t\right)>1-\varepsilon \text { and } N\left(\xi_{n}, \xi_{m}, t\right)<\varepsilon .
$$

(2). $(X, M, N, *, \diamond)$ is called complete whenever every Cauchy sequence is convergent with respect to the topology $\tau_{(M, N)}$.

Remark 1.5 Note that, if $(M, N)$ is called an intuitionistic fuzzy metric space on $X$ and $\left\{\xi_{n}\right\}$ is a sequence in X such that

$$
\lim _{m, n \rightarrow \infty} M\left(\xi_{n}, \xi_{m}, t\right)=1 \text { and } \lim _{m, n \rightarrow \infty} N\left(\xi_{n}, \xi_{m}, t\right)=0
$$

for all $t>0$ as from (IFMS1) of Definition 1.3, we know that $M(\xi, \eta, t)+N(\xi, \eta, t) \leq 1$ for all $\xi, \eta \in X$ and $t>0$.

Let $(X, M, N, *, \diamond)$ be an intuitionistic fuzzy metric space. According to [40, 43], the fuzzy metric $(M, N)$ is called triangular whenever

$$
\begin{gather*}
\frac{1}{M(\xi, \eta, t)}-1 \leq \frac{1}{M(\xi, \sigma, t)}-1+\frac{1}{M(\sigma, \eta, t)}-1 \text { and }  \tag{1.1}\\
N(\xi, \eta, t) \leq N(\xi, \sigma, t)+N(\sigma, \eta, t) \tag{1.2}
\end{gather*}
$$

for all $\xi, \eta, \sigma \in X$ and $t>0$.
Example 1.6 Let $X=\{(0,0),(0,4),(4,0),(4,5),(5,4)\}$ endowed with the metric $d: X \times X \rightarrow$ $[0,+\infty)$ given by

$$
\begin{equation*}
d\left(\left(\xi_{1}, \xi_{2}\right),\left(\eta_{1}, \eta_{2}\right)\right)=\left|\xi_{1}-\eta_{1}\right|+\left|\xi_{2}-\eta_{2}\right| \tag{1.3}
\end{equation*}
$$

for all $\left(\xi_{1}, \xi_{2}\right),\left(\eta_{1}, \eta_{2}\right) \in X$. Define intuitionistic fuzzy metric by

$$
\begin{align*}
& M\left(\left(\xi_{1}, \xi_{2}\right),\left(\eta_{1}, \eta_{2}\right), t\right)=\frac{t}{t+d\left(\left(\xi_{1}, \xi_{2}\right),\left(\eta_{1}, \eta_{2}\right)\right)} \text { and }  \tag{1.4}\\
& N\left(\left(\xi_{1}, \xi_{2}\right),\left(\eta_{1}, \eta_{2}\right), t\right)=\frac{d\left(\left(\xi_{1}, \xi_{2}\right),\left(\eta_{1}, \eta_{2}\right)\right)}{t+d\left(\left(\xi_{1}, \xi_{2}\right),\left(\eta_{1}, \eta_{2}\right)\right)} \tag{1.5}
\end{align*}
$$

for all $\left(\xi_{1}, \xi_{2}\right),\left(\eta_{1}, \eta_{2}\right) \in X$ and $t>0$, where

$$
a * b=\min \{a, b\} \quad \text { and } a \diamond b=\operatorname{ma\xi }\{a, b\} .
$$

Then $X$ is a complete triangular intuitionistic fuzzy metric space.
The following definitions will be needed in the sequel.

TRIANGULAR INTUITIONISTIC FUZZY METRIC SPACES
Definition 1.7 (see [20]) Let $F$ and $G$ be two self-mappings on a nonempty set $X$. Then $F$ and T are said to be weakly compatible if they commute at all of their coincidence points; that is, $F \omega=G \omega$ for some $\omega \in X$ and then $F G \omega=G F \omega$.

Definition 1.8 (see [15]) Two finite families of self-mappings $\left\{F_{i}\right\}_{i=1}^{m}$ and $\left\{G_{k}\right\}_{k=1}^{n}$ of a nonempty set $X$ are said to be pairwise commuting if

1. $F_{i} F_{j}=F_{j} F_{i}, i, j \in\{1,2, \ldots \ldots, m\}$
2. $G_{k} G_{l}=G_{l} G_{k}, k, l \in\{1,2, \ldots, p\}$
3. $F_{i} G_{k}=G_{k} F_{i}, i \in\{1,2, \ldots, m\}, k \in\{1,2, . ., p\}$.

The following lemma is helpful in proving our results which can be found in [2].
Lemma 1.9 Let $F, G$, and $f$ be self-mappings on a nonempty set $X$ with $F, G$, and $f$ having a unique point of coincidence in $X$. If $(F, f)$ and $(G, f)$ are weakly compatible. Then $F, G$ and $f$ have a unique common fixed point.

Implicit relations: Simple and natural way to unify and prove in a simple manner several metrical fixed-point theorems is to consider an implicit contraction type condition instead of the usual explicit contractive conditions. Popa [33, 35] proved several fixed-point theorems satisfying suitable implicit relations. For proving such results, Popa [33, 35] considered $\Psi$ to be the set of all continuous functions

$$
\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right): \mathbb{R}_{+}^{6} \rightarrow \mathbb{R}
$$

satisfying the following conditions:
$\left(\psi_{1}\right) \cdot \psi$ is non-increasing in variables $u_{5}$ and $u_{6}$.
$\left(\Psi_{2}\right)$. there exists $k \in(0,1)$ such that for $u, v \geq 0$ with

$$
\begin{aligned}
& \quad\left(\psi_{2 \mathrm{a}}\right) \cdot \psi(u, v, v, u, u+v, 0) \leq 0 \text { or } \\
& \quad\left(\psi_{2 \mathrm{~b}}\right) \cdot \psi(u, v, u, v, 0, u+v) \leq 0 \Rightarrow u \leq k v, \\
& \left(\psi_{3}\right) \cdot \psi(u, u, 0,0, u, u)>0
\end{aligned}
$$

Some of the following examples of such functions $\psi$ satisfying $\left(\Psi_{1}\right),\left(\psi_{2}\right)$ and $\left(\Psi_{3}\right)$ are taken from Popa [35] and Imdad and Ali [13].

Example 1.10 Define $\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right): \mathbb{R}_{+}^{6} \rightarrow \mathbb{R}$ as:

$$
\begin{equation*}
\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)=u_{1}-k \operatorname{ma\xi }\left\{u_{2}, u_{3}, u_{4}, \frac{1}{2}\left(u_{5}+u_{6}\right)\right\} \tag{1.6}
\end{equation*}
$$

where $k \in(0,1)$.

$$
\begin{equation*}
\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)=u_{1}^{2}-u_{1}\left(a u_{2}+b u_{3}+c u_{4}\right)-d u_{5} u_{6} \tag{1.7}
\end{equation*}
$$

where $a>0, b, c, d \geq 0, a+b+c<1, a+d<1$.

$$
\begin{equation*}
\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)=u_{1}^{3}-a u_{1}^{2} u_{2}-b u_{1} u_{2} u_{3}+c u_{5}^{2} u_{6}-d u_{5} u_{6}^{2} \tag{1.8}
\end{equation*}
$$

where $a>0, b, c, d \geq 0, a+b<1, a+c+d<1$.

$$
\begin{equation*}
\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)=u_{1}^{3}-k\left(\frac{u_{3}^{2} u_{4}^{2}+u_{5}^{2} u_{6}^{2}}{u_{2}+u_{3}+u_{4}+1}\right) \tag{1.9}
\end{equation*}
$$

where $k \in(0,1)$.

$$
\begin{equation*}
\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)=u_{1}^{2}-a u_{2}^{2}-b\left(\frac{u_{5} u_{6}}{u_{3}^{2}+u_{4}^{2}+1}\right) \tag{1.10}
\end{equation*}
$$

where $a>0, b \geq 0, a+b<1$.

$$
\begin{gather*}
\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)=u_{1}^{2}-\operatorname{ama} \xi\left\{u_{2}^{2} u_{3}^{2} u_{4}^{2}\right\}-b \operatorname{ma\xi }\left\{u_{3} u_{5}, u_{4} u_{6}\right\}  \tag{1.11}\\
-c u_{5} u_{6}
\end{gather*}
$$

where $a>0, b, c \geq 0, a+2 b<1, a+c<1$.

$$
\begin{equation*}
\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)=u_{1}-k \operatorname{ma\xi }\left\{u_{2}, u_{3}, u_{4}, \frac{1}{2} u_{5}, \frac{1}{2} u_{6}\right\} \tag{1.12}
\end{equation*}
$$

where $k \in(0,1)$.

$$
\begin{equation*}
\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)=u_{1}-k \operatorname{ma\xi }\left\{u_{2}, \frac{u_{3}+u_{4}}{2}, \frac{u_{5}+u_{6}}{2}\right\} \tag{1.13}
\end{equation*}
$$

where $k \in(0,1)$.

$$
\begin{equation*}
\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)=u_{1}-\left(a u_{2}+b u_{3}+c u_{4}+d u_{5}+c u_{6}\right) \tag{1.14}
\end{equation*}
$$

where $d, e \geq 0, a+b+c+d+e<1$.

$$
\begin{equation*}
\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)=u_{1}-\frac{k}{2} m a \xi\left\{u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right\} \tag{1.15}
\end{equation*}
$$

where $k \in(0,1)$.

$$
\begin{equation*}
\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)=u_{1}-\left[a u_{2}+b u_{3}+c u_{4}+d\left(u_{5}+u_{6}\right)\right] \tag{1.16}
\end{equation*}
$$

where $d \geq 0, a+b+c+2 d<1$.

## TRIANGULAR INTUITIONISTIC FUZZY METRIC SPACES

Since verifications of requirements $\left(\Psi_{1}\right),\left(\Psi_{2}\right)$ and $\left(\Psi_{3}\right)$ for Examples (2.6)-(2.16) are straightforward, hence details are omitted. Here one may further notice that some other well known contraction conditions ([10, 14, and 18]) can also be deduced as particular cases of implicit relation of Popa [35]. In order to strengthen this viewpoint, we add some more examples to this effect and utilize them to demonstrate how this implicit relation can cover several other known contractive conditions and is also good enough to yield further unknown natural contractive conditions as well.

Example 1.11 Define $\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right): \mathbb{R}_{+}^{6} \rightarrow \mathbb{R}$ as:

$$
\begin{align*}
& \psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)  \tag{1.17}\\
& \qquad=\left\{\begin{array}{c}
u_{1}-a_{1} \frac{u_{3}^{2}+u_{4}^{2}}{u_{3}+u_{4}}-a_{2} u_{2}-a_{3}\left(u_{5}+u_{6}\right), \text { if } u_{3}+u_{4} \neq 0 \\
u_{1}, \\
\text { if } u_{3}+u_{4}=0
\end{array}\right.
\end{align*}
$$

where $a_{i} \geq 0(i=1,2,3)$ with at least one $a_{i}$ non-zero and $a_{1}+a_{2}+2 a_{3}<1$. ( $\Psi_{1}$ ). Obviously, $\psi$ is non-increasing in variables $u_{5}$ and $u_{6}$. $\left(\Psi_{2 \mathrm{a}}\right)$. Let $u>0$. Then

$$
\psi(u, v, v, u, u+v, 0)=u-a_{1} \frac{v^{2}+u^{2}}{v+u}-a_{2} v-a_{3}(u+v) \leq 0 .
$$

If $u \geq v$, then

$$
u \leq\left(a_{1}+a_{2}+2 a_{3}\right) u<u
$$

which is contradiction. Hence $u<v$ and $u \leq k v$ where $k \in(0,1)$. $\left(\Psi_{2 \mathrm{~b}}\right)$. Similar argument as in $\left(\psi_{2 \mathrm{a}}\right) \cdot\left(\Psi_{3}\right) \cdot \psi(u, u, 0,0, u, u)=u>0$ for all $u>0$.

Example 1.12 Define $\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right): \mathbb{R}_{+}^{6} \rightarrow \mathbb{R}$ as:

$$
\begin{align*}
& \psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)  \tag{1.18}\\
& \qquad= \begin{cases}u_{1}-a_{1} u_{2}-\frac{a_{2} u_{3} u_{4}+a_{3} u_{5} u_{6}}{u_{3}+u_{4}}, & \text { if } u_{3}+u_{4} \neq 0 \\
u_{1}, & \text { if } u_{3}+u_{4}=0\end{cases}
\end{align*}
$$

where $a_{1}, a_{2}, a_{3} \geq 0$ such that $1<2 a_{1}+a_{2}<2$.
Example 1.13 Define $\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right): \mathbb{R}_{+}^{6} \rightarrow \mathbb{R}$ as:

$$
\begin{equation*}
\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)=u_{1}-a_{1}\left[a_{2} \operatorname{ma\xi }\left\{u_{2}, u_{3}, u_{4}, \frac{1}{2}\left(u_{5}+u_{6}\right)\right\}\right. \tag{1.19}
\end{equation*}
$$

$$
\left.+\left(1-a_{2}\right)\left[\operatorname{ma\xi }\left\{u_{2}^{1}, u_{3} u_{4}, u_{5} u_{6}, \frac{u_{3} u_{6}}{2}, \frac{u_{4} u_{5}}{2}\right\}\right]^{\frac{1}{2}}\right]
$$

where $a_{1} \in(0,1)$ and $0 \leq a_{2} \leq 1$.
Example 1.14 Define $\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right): \mathbb{R}_{+}^{6} \rightarrow \mathbb{R}$ as:

$$
\begin{align*}
& \psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)  \tag{1.20}\\
& \quad=u_{2}^{1}-a_{1} \operatorname{ma\xi }\left\{u_{2}^{2}, u_{3}^{2}, u_{4}^{2}\right\}-a_{2} \operatorname{ma\xi }\left\{\frac{u_{3} u_{6}}{2}, \frac{u_{4} u_{5}}{2}\right\}-a_{3} u_{5} u_{6}
\end{align*}
$$

where $a_{1}, a_{2}, a_{3} \geq 0$ and $a_{1}+a_{2}+a_{3}<1$.
Very recently, Popa et al. [34] proved several fixed-point theorems satisfying suitable implicit relations in which Husain and Sehgal [11] type contraction conditions ([6, 22, 30, 41]) can be deduced from similar implicit relations in addition to all earlier ones if there is a slight modification in condition $\left(\Psi_{1}\right)$ as follows:
$\left(\psi_{1}\right)^{\prime}$ Obviously, $\psi$ is decreasing in variables $u_{2}, \ldots \ldots, u_{6}$.
Hereafter, let $\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right): \mathbb{R}_{+}^{6} \rightarrow \mathbb{R}$ be a continuous function which satisfies the conditions $\left(\Psi_{1}\right)^{\prime},\left(\Psi_{2}\right)$ and $\left(\Psi_{3}\right)$ and $\mathcal{F}$ be the family of such functions. In this paper, we employ such implicit relation to prove our results. But before we proceed further, let us furnish some examples to highlight the utility of the modifications instrumented herein.

Example 1.15 Define $\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right): \mathbb{R}_{+}^{6} \rightarrow \mathbb{R}$ as:

$$
\begin{equation*}
\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)=u_{1}-\phi\left(\operatorname{ma\xi }\left\{u_{2}, u_{3}, u_{4}, \frac{1}{2}\left(u_{5}+u_{6}\right)\right\}\right) \tag{1.21}
\end{equation*}
$$

where $\phi: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$is an increasing upper semi-continuous function with $\phi(0)=0$ and $\phi(u)<u$ for each $u>0$.
( $\left.\Psi_{1}\right)^{\prime}$ Obviously, $\psi$ is decreasing in variables $u_{2}, \ldots, u_{6}$.
$\left(\psi_{2 \mathrm{a}}\right)$. Let $u>0$. Then

$$
\psi(u, v, v, u, u+v, 0)=u-\phi\left(\operatorname{ma\xi }\left\{v, v, u, \frac{1}{2}(v+u)\right\}\right)<0 .
$$

If $u \geq v$, then

$$
u \leq \phi(u)<u
$$

TRIANGULAR INTUITIONISTIC FUZZY METRIC SPACES
which is contradiction. Hence $u<v$ and $u \leq k v$ where $k \in(0,1)$.
$\left(\Psi_{2 \mathrm{~b}}\right)$. Similar argument as in $\left(\Psi_{2 \mathrm{a}}\right)$.

$$
\begin{aligned}
\left(\psi_{3}\right) . \quad \psi(u, u, 0,0, u, u) & =u-\phi\left(\operatorname{ma\xi }\left\{u, 0,0, \frac{1}{2}(u+u)\right\}\right) \\
& =u-\phi(u)>0 \text { for all } u>0
\end{aligned}
$$

Example 1.16 Define $\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right): \mathbb{R}_{+}^{6} \rightarrow \mathbb{R}$ as:

$$
\begin{equation*}
\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)=u_{1}-\phi\left(u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right) \tag{1.22}
\end{equation*}
$$

where $\phi: \mathbb{R}_{+}^{5} \rightarrow \mathbb{R}^{+}$is an upper semi-continuous and non-decreasing function in each coordinate variable such that $\phi(u, u, a u, b u, c u)<u$ for each $u>0$ and $a, b, c \geq 0$ with $a+$ $b+c \leq 3$.

Example 1.17 Define $\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right): \mathbb{R}_{+}^{6} \rightarrow \mathbb{R}$ as:

$$
\begin{equation*}
\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)=u_{1}^{2}-\phi\left(u_{2}^{2}, u_{3} u_{4}, u_{5} u_{6}, u_{3} u_{6}, u_{4} u_{5}\right) \tag{1.23}
\end{equation*}
$$

where $\phi: \mathbb{R}_{+}^{5} \rightarrow \mathbb{R}^{+}$is an upper semi-continuous and non-decreasing function in each coordinate variable such that $\phi(u, u, a u, b u, c u)<u$ for each $u>0$ and $a, b, c \geq 0$ with $a+$ $b+c \leq 3$.

Here it may be noticed that all earlier mentioned examples continue to enjoy the format of modified implicit relation as adopted herein. Motivated by the fact that a fixed-point of any map on metric spaces can always be viewed as a common fixed-point of that map and identity map on the space. Jungck [20] proved the interesting generalization of celebrated Banach contraction principle. While proving his result, Jungck [20] replaced identity map with a continuous mapping. In [30], Imdad and Ali established a general common fixed-point theorem for a pair of mappings using a suitable implicit function without the requirement of the containment of ranges.

In this paper, we present a new general common fixed-point theorem for two pair of mappings under a different set of conditions using the idea of weakly compatible mappings satisfying a general class of contractions defined by an implicit relation in the frame work of triangular
intuitionistic fuzzy metric space, which unify, extend and generalize most of the existing relevant common fixed-point theorems from the literature. Some related results and illustrative an example to highlight the realized improvements is also furnished.

## 2. Main Results

The following theorem is our main result.
Theorem 2.1 Let $F, G, f$ and $g$ be four self-maps of a triangular intuitionistic fuzzy metric space $(X, M, N, *, \diamond)$ with $\overline{G(X)} \subseteq f(X)$ and $\overline{F(X)} \subseteq g(X)$ and for all $\xi, \eta \in X, t>0$ and some $\psi \in \Psi$,

$$
\begin{align*}
& \psi\left(\frac{1}{M(F \xi, G \eta, t)}-1, \frac{1}{M(f \xi, g \eta, t)}-1, \frac{1}{M(f \xi, F \xi, t)}-1\right.  \tag{2.1}\\
& \left.\frac{1}{M(g \eta, G \eta, t)}-1, \frac{1}{M(f \xi, G \eta, t)}-1, \frac{1}{M(F \xi, g \eta, t)}-1\right) \leq 0
\end{align*}
$$

If one of $\overline{G(X)}$ and $\overline{F(X)}$ is a complete subspace of $X$, then $(F, f)$ and $(G, g)$ have a unique point of coincidence inX. Moreover, if $(F, f)$ and $(G, g)$ are weakly compatible, then $F, G, f$ and $g$ have a unique common fixed-point in $X$.

Proof Let $\xi_{0} \in X$ be arbitrary point. Because $G(X) \subseteq \overline{G(X)}$ and $F(X) \subseteq \overline{F(X)}$, we have $F(X) \subseteq f(X)$ and $G(X) \subseteq g(X)$. Hence one can inductively define the sequences $\left\{\xi_{n}\right\} \subset X$ and $\left\{\eta_{n}\right\} \subset X$ in the following way:

$$
\begin{align*}
\eta_{2 n-1} & =F \xi_{2 n-1}=g \xi_{2 n},  \tag{2.2}\\
\eta_{2 n} & =G \xi_{2 n}=f \xi_{2 n+1}, \forall n \in \mathbb{N} .
\end{align*}
$$

From (2.1) with $\xi=\xi_{2 n+1}$ and $\eta=\xi_{2 n+2}$, we get for all $t>0$ and all $n \in \mathbb{N}$,

$$
\begin{align*}
& \psi\left(\frac{1}{M\left(F \xi_{2 n+1}, G \xi_{2 n+2}, t\right)}-1, \frac{1}{M\left(f \xi_{2 n+1}, g \xi_{2 n+2}, t\right)}-1, \frac{1}{M\left(f \xi_{2 n+1}, F \xi_{2 n+1}, t\right)}-1\right.  \tag{2.3}\\
& \left.\frac{1}{M\left(g \xi_{2 n+2}, G \xi_{2 n+2}, t\right)}-1, \frac{1}{M\left(f \xi_{2 n+1}, G \xi_{2 n+2}, t\right)}-1, \frac{1}{M\left(F \xi_{2 n+1}, g \xi_{2 n+2}, t\right)}-1\right) \leq 0
\end{align*}
$$

We have

$$
\psi\left(\frac{1}{M\left(\eta_{2 n+1}, \eta_{2 n+2}, t\right)}-1, \frac{1}{M\left(\eta_{2 n}, \eta_{2 n+1}, t\right)}-1, \frac{1}{M\left(\eta_{2 n}, \eta_{2 n+1}, t\right)}-1,\right.
$$

TRIANGULAR INTUITIONISTIC FUZZY METRIC SPACES

$$
\left.\frac{1}{M\left(\eta_{2 n+1}, \eta_{2 n+2}, t\right)}-1, \frac{1}{M\left(\eta_{2 n}, \eta_{2 n+2}, t\right)}-1, \frac{1}{M\left(\eta_{2 n+1}, \eta_{2 n+1}, t\right)}-1\right) \leq 0
$$

That is,

$$
\begin{gather*}
\psi\left(\frac{1}{M\left(\eta_{2 n+1}, \eta_{2 n+2}, t\right)}-1, \frac{1}{M\left(\eta_{2 n}, \eta_{2 n+1}, t\right)}-1, \frac{1}{M\left(\eta_{2 n}, \eta_{2 n+1}, t\right)}-1,\right.  \tag{2.4}\\
\left.\frac{1}{M\left(\eta_{2 n+1}, \eta_{2 n+2}, t\right)}-1, \frac{1}{M\left(\eta_{2 n}, \eta_{2 n+2}, t\right)}-1,0\right) \leq 0,
\end{gather*}
$$

Using the fact that $\psi$ is non-decreasing in variable $u_{5}$ and $u_{6}$, we have

$$
\begin{equation*}
\frac{1}{M\left(\eta_{2 n}, \eta_{2 n+2}, t\right)}-1 \leq \frac{1}{M\left(\eta_{2 n}, \eta_{2 n+1}, t\right)}-1+\frac{1}{M\left(\eta_{2 n+1}, \eta_{2 n+2}, t\right)}-1 \tag{2.5}
\end{equation*}
$$

From (2.4), we derive that

$$
\begin{align*}
& \psi\left(\frac{1}{M\left(\eta_{2 n+1}, \eta_{2 n+2}, t\right)}-1, \frac{1}{M\left(\eta_{2 n}, \eta_{2 n+1}, t\right)}-1, \frac{1}{M\left(\eta_{2 n}, \eta_{2 n+1}, t\right)}-1\right.  \tag{2.6}\\
& \left.\frac{1}{M\left(\eta_{2 n+1}, \eta_{2 n+2}, t\right)}-1, \frac{1}{M\left(\eta_{2 n}, \eta_{2 n+1}, t\right)}-1+\frac{1}{M\left(\eta_{2 n+1}, \eta_{2 n+2}, t\right)}-1,0\right) \leq 0
\end{align*}
$$

Now, using property $\left(\psi_{2 \mathrm{a}}\right)$, we have

$$
\begin{equation*}
\frac{1}{M\left(\eta_{2 n+1}, \eta_{2 n+2}, t\right)}-1 \leq k\left(\frac{1}{M\left(\eta_{2 n}, \eta_{2 n+1}, t\right)}-1\right) \tag{2.7}
\end{equation*}
$$

Again, using (2.1), with $\xi=\xi_{2 n}$ and $\eta=\xi_{2 n+1}$, we get for all $t>0$ and all $n \in \mathbb{N}$,

$$
\begin{align*}
& \psi\left(\frac{1}{M\left(F \xi_{2 n}, G \xi_{2 n+1}, t\right)}-1, \frac{1}{M\left(f \xi_{2 n}, g \xi_{2 n+1}, t\right)}-1, \frac{1}{M\left(f f \xi_{2 n}, F \xi_{2 n}, t\right)}-1\right.  \tag{2.8}\\
& \left.\frac{1}{M\left(g \xi_{2 n+1}, G \xi_{2 n+1}, t\right)}-1, \frac{1}{M\left(f \xi_{2 n}, G \xi_{2 n+1}, t\right)}-1, \frac{1}{M\left(F \xi_{2 n}, g \xi_{2 n+1}, t\right)}-1\right) \leq 0
\end{align*}
$$

That is,

$$
\begin{gather*}
\psi\left(\frac{1}{M\left(\eta_{2 n}, \eta_{2 n+1}, t\right)}-1, \frac{1}{M\left(\eta_{2 n-1}, \eta_{2 n}, t\right)}-1, \frac{1}{M\left(\eta_{2 n-1}, \eta_{2 n}, t\right)}-1,\right.  \tag{2.9}\\
\left.\frac{1}{M\left(\eta_{2 n}, \eta_{2 n+1}, t\right)}-1, \frac{1}{M\left(\eta_{2 n-1}, \eta_{2 n+1}, t\right)}-1,0\right) \leq 0
\end{gather*}
$$

Keeping in mind that $\psi$ is non-decreasing in variable $u_{5}$ and $u_{6}$, we have

$$
\begin{equation*}
\frac{1}{M\left(\eta_{2 n-1}, \eta_{2 n+1}, t\right)}-1 \leq \frac{1}{M\left(\eta_{2 n-1}, \eta_{2 n}, t\right)}-1+\frac{1}{M\left(\eta_{2 n}, \eta_{2 n+1}, t\right)}-1 \tag{2.10}
\end{equation*}
$$

From (2.9), we obtain

$$
\begin{equation*}
\psi\left(\frac{1}{M\left(\eta_{2 n}, \eta_{2 n+1}, t\right)}-1, \frac{1}{M\left(\eta_{2 n-1}, \eta_{2 n}, t\right)}-1, \frac{1}{M\left(\eta_{2 n-1}, \eta_{2 n}, t\right)}-1\right. \tag{2.11}
\end{equation*}
$$

$$
\left.\frac{1}{M\left(\eta_{2 n}, \eta_{2 n+1}, t\right)}-1, \frac{1}{M\left(\eta_{2 n-1}, \eta_{2 n}, t\right)}-1+\frac{1}{M\left(\eta_{2 n}, \eta_{2 n+1}, t\right)}-1,0\right) \leq 0,
$$

yielding thereby $\left(\right.$ due to $\left.\left(\Psi_{2 \mathrm{a}}\right)\right)$,

$$
\begin{equation*}
\frac{1}{M\left(\eta_{2 n}, \eta_{2 n+1}, t\right)}-1 \leq k\left(\frac{1}{M\left(\eta_{2 n-1}, \eta_{2 n}, t\right)}-1\right) . \tag{2.12}
\end{equation*}
$$

Combining (2.7) and (2.12), we have

$$
\begin{equation*}
\frac{1}{M\left(\eta_{2 n+1}, \eta_{2 n+2}, t\right)}-1 \leq k^{2}\left(\frac{1}{M\left(\eta_{2 n-1}, \eta_{2 n}, t\right)}-1\right) \tag{2.13}
\end{equation*}
$$

Now by induction, we obtain for each $n=0,1,2, \ldots$

$$
\begin{align*}
\frac{1}{M\left(\eta_{2 n+1}, \eta_{2 n+2}, t\right)}-1 & \leq k\left(\frac{1}{M\left(\eta_{2 n}, \eta_{2 n+1}, t\right)}-1\right)  \tag{2.14}\\
& \leq \cdots \leq k^{2 n+1}\left(\frac{1}{M\left(\eta_{0}, \eta_{1}, t\right)}-1\right)
\end{align*}
$$

and by a routine calculation, we have,

$$
\begin{align*}
\frac{1}{M\left(\eta_{n+1}, \eta_{n+2}, t\right)}-1 & \leq k\left(\frac{1}{M\left(\eta_{n}, \eta_{n+1}, t\right)}-1\right)  \tag{2.15}\\
& \leq \cdots \leq k^{n+1}\left(\frac{1}{M\left(\eta_{0}, \eta_{1}, t\right)}-1\right)
\end{align*}
$$

Hence for each $n>m$, we obtain

$$
\begin{align*}
\frac{1}{M\left(\eta_{n}, \eta_{m}, t\right)}-1 & \leq \frac{1}{M\left(\eta_{n}, \eta_{n-1}, t\right)}-1+\frac{1}{M\left(\eta_{n-1}, \eta_{n-2}, t\right)}-1+\cdots+\frac{1}{M\left(\eta_{m+1}, \eta_{m}, t\right)}-1  \tag{2.16}\\
& \leq\left(k^{n-1}+k^{n-2}+\cdots+k^{m}\right)\left(\frac{1}{M\left(\eta_{0}, \eta_{1}, t\right)}-1\right) \\
& \leq \frac{k^{m}}{1-k}\left(\frac{1}{M\left(\eta_{0}, \eta_{1}, t\right)}-1\right)
\end{align*}
$$

Therefore, $\left\{\eta_{n}\right\}$ is a Cauchy sequence. Assume that $\overline{G(X)}$ is complete. Observe that the subsequence $\left\{\eta_{2 n}\right\}$ is a Cauchy sequence which is contained in $\overline{G(X)}$ must a limit $\omega^{*}$ in $f(X)$, that is,

$$
\begin{align*}
\lim _{n \rightarrow \infty} \eta_{2 n} & =\lim _{n \rightarrow \infty} G \xi_{2 n} \\
& =\lim _{n \rightarrow \infty} f \xi_{2 n+1} \in \overline{G(X)} \subseteq f(X) \subset X, \\
\lim _{n \rightarrow \infty} \eta_{2 n} & =\lim _{n \rightarrow \infty} G \xi_{2 n} \tag{2.17}
\end{align*}
$$

$$
=\lim _{n \rightarrow \infty} f \xi_{2 n+1}=\omega^{*} \in f(X) .
$$

It is easy to see

$$
\begin{align*}
\omega^{*} & =\lim _{n \rightarrow \infty} \eta_{n}=\lim _{n \rightarrow \infty} G \xi_{2 n}  \tag{2.18}\\
& =\lim _{n \rightarrow \infty} f \mathrm{x}_{2 n+1}=\lim _{n \rightarrow \infty} G \xi_{2 n} \\
& =\lim _{n \rightarrow \infty} f \xi_{2 n+1}=\lim _{n \rightarrow \infty} F \xi_{2 n-1}=\lim _{n \rightarrow \infty} g \xi_{2 n}
\end{align*}
$$

Consequently, we can find $\omega \in X$ such that $f \omega=\omega^{*}$. We assert that $F \omega=f \omega=\omega^{*}$. If not, then $M\left(F \omega, \omega^{*}, t\right)<1$. Using (2.1), with $\xi=\omega$ and $\eta=\xi_{2 n}$, we have

$$
\begin{align*}
& \psi\left(\frac{1}{M\left(F \omega, G \xi_{2 n}, t\right)}-1, \frac{1}{M\left(f \omega, g \xi_{2 n}, t\right)}-1, \frac{1}{M(f \omega, F \omega, t)}-1\right.  \tag{2.19}\\
\Rightarrow \quad & \left.\frac{1}{M\left(g \xi_{2 n}, G \xi_{2 n}, t\right)}-1, \frac{1}{M\left(f \omega, G \xi_{2 n}, t\right)}-1, \frac{1}{M\left(S \omega, g \xi_{2 n}, t\right)}-1\right) \leq 0 \\
\Rightarrow & \psi\left(\frac{1}{M\left(F \omega, \eta_{2 n}, t\right)}-1, \frac{1}{M\left(f \omega, \eta_{2 n-1}, t\right)}-1, \frac{1}{M(f \omega, F \omega, t)}-1\right. \\
& \left.\frac{1}{M\left(\eta_{2 n-1}, \eta_{2 n}, t\right)}-1, \frac{1}{M\left(f \omega, \eta_{2 n}, t\right)}-1, \frac{1}{M\left(F \omega, \eta_{2 n-1}, t\right)}-1\right) \leq 0
\end{align*}
$$

Letting $n \rightarrow+\infty$ in the above inequality, using (2.18) and the continuity of $\psi$, we have

$$
\begin{equation*}
\psi\left(\frac{1}{M\left(F \omega, \omega^{*}, t\right)}-1,0, \frac{1}{M\left(\omega^{*}, F \omega, t\right)}-1,0,0, \frac{1}{M\left(F \omega, \omega^{*}, t\right)}-1\right) \leq 0 \tag{2.20}
\end{equation*}
$$

yielding thereby (due to $\left.\left(\psi_{2 b}\right)\right), \frac{1}{M\left(F \omega, \omega^{*}, t\right)}-1 \leq 0$, that is $M\left(F \omega, \omega^{*}, t\right)=1$, which is a contradiction. Then we have $F \omega=f \omega=\omega^{*}$, which shows that $\omega$ is a coincidence point of $F$ and $f$, that is $\omega^{*}$ is a point of coincidence of $F$ and $f$. Since $\omega^{*}=F \omega \in F(X) \subseteq \overline{F(X)} \subseteq g(X)$, there exists $\omega^{\prime} \in X$ such that $g \omega^{\prime}=\omega^{*}$. We claim that $G \omega^{\prime}=\omega^{*}$. If not, then $M\left(G \omega^{\prime}, \omega^{*}, t\right)<1$. Using (2.1), with $\xi=\omega$ and $\eta=\omega^{\prime}$, we have

$$
\begin{aligned}
& \psi\left(\frac{1}{M\left(F \omega, G \omega^{\prime}, t\right)}-1, \frac{1}{M\left(f \omega, g \omega^{\prime}, t\right)}-1, \frac{1}{M(f \omega, F \omega, t)}-1\right. \\
& \left.\frac{1}{M\left(g \omega^{\prime}, G \omega^{\prime}, t\right)}-1, \frac{1}{M\left(f \omega, G \omega^{\prime}, t\right)}-1, \frac{1}{M\left(F \omega, g \omega^{\prime}, t\right)}-1\right) \leq 0
\end{aligned}
$$

That is,

$$
\begin{equation*}
\psi\left(\frac{1}{M\left(\omega^{*}, G \omega^{\prime}, t\right)}-1,0,0, \frac{1}{M\left(\omega^{*}, G \omega^{\prime}, t\right)}-1, \frac{1}{M\left(\omega^{*}, G \omega^{\prime}, t\right)}-1,0\right) \leq 0 \tag{2.21}
\end{equation*}
$$

yielding thereby (due to $\left.\left(\psi_{2 a}\right)\right), \frac{1}{M\left(\omega^{*}, G \omega^{\prime}, t\right)}-1 \leq 0$, then $M\left(\omega^{*}, G \omega^{\prime}, t\right)=1$. Thus, our supposition that $M\left(G \omega^{\prime}, \omega^{*}, t\right)<1$ was wrong. Therefore $G \omega^{\prime}=g \omega^{\prime}=\omega^{*}$, which shows that $\omega^{\prime}$ is a coincidence point of $G$ and $g$, that is $\omega^{*}$ is a point of coincidence of $G$ and $g$. Now, suppose that $\omega_{*}$ is another point of coincidence of $F$ and $f$, that is $\omega_{*}=F \bar{\omega}=f \bar{\omega}$ for some $\bar{\omega} \in X$. Using (2.1), we have

$$
\begin{align*}
& \psi \frac{1}{M\left(F \bar{\omega}, G \omega^{\prime}, t\right)}-1, \frac{1}{M\left(f \bar{\omega}, g \omega^{\prime}, t\right)}-1, \frac{1}{M(f \bar{\omega}, F \bar{\omega}, t)}-1,  \tag{2.22}\\
& \left.\frac{1}{M\left(g \omega^{\prime}, G \omega^{\prime}, t\right)}-1, \frac{1}{M\left(f \bar{\omega}, G \omega^{\prime}, t\right)}-1, \frac{1}{M\left(F \bar{\omega}, g \omega^{\prime}, t\right)}-1\right) \leq 0,
\end{align*}
$$

This implies that

$$
\begin{aligned}
& \psi\left(\frac{1}{M\left(\omega_{*}, \omega^{*}, t\right)}-1, \frac{1}{M\left(\omega_{*}, \omega^{*}, t\right)}-1, \frac{1}{M\left(\omega_{*}, \omega_{*}, t\right)}-1\right. \\
& \left.\frac{1}{M\left(\omega^{*}, \omega^{*}, t\right)}-1, \frac{1}{M\left(\omega_{*}, \omega^{*}, t\right)}-1, \frac{1}{M\left(\omega_{*}, \omega^{*}, t\right)}-1\right) \leq 0
\end{aligned}
$$

That is,

$$
\begin{align*}
& \psi\left(\frac{1}{M\left(\omega_{*}, \omega^{*}, t\right)}-1, \frac{1}{M\left(\omega_{*}, \omega^{*}, t\right)}-1,0\right.  \tag{2.23}\\
& \left.0, \frac{1}{M\left(\omega_{*}, \omega^{*}, t\right)}-1, \frac{1}{M\left(\omega_{*}, \omega^{*}, t\right)}-1\right) \leq 0
\end{align*}
$$

Due to $\left(\psi_{3}\right)$, we get a contradiction, if $\omega_{*} \neq \omega^{*}$. Hence point of coincidence of $F$ and $f$ is unique. Now, suppose that $\omega_{1}^{*}$ is another point of coincidence of $g$ and $G$, that is $\omega_{1}^{*}=G \omega_{1}=$ $g \omega_{1}$ for some $\omega_{1} \in X$. Using (2.1), we have

$$
\begin{aligned}
& \psi\left(\frac{1}{M\left(F \omega, G \omega_{1}, t\right)}-1, \frac{1}{M\left(f \omega, g \omega_{1}, t\right)}-1, \frac{1}{M(f \omega, F \omega, t)}-1,\right. \\
& \left.\frac{1}{M\left(g \omega_{1}, G \omega_{1}, t\right)}-1, \frac{1}{M\left(f \omega, G \omega_{1}, t\right)}-1, \frac{1}{M\left(F \omega, g \omega_{1}, t\right)}-1\right) \leq 0
\end{aligned}
$$

Thus,

$$
\begin{aligned}
& \psi\left(\frac{1}{M\left(\omega^{*}, \omega_{1}^{*}, t\right)}-1, \frac{1}{M\left(\omega^{*}, \omega_{1}^{*}, t\right)}-1, \frac{1}{M\left(\omega^{*}, \omega^{*}, t\right)}-1\right. \\
& \left.\frac{1}{M\left(\omega_{1}^{*}, \omega_{1}^{*}, t\right)}-1, \frac{1}{M\left(\omega^{*}, \omega_{1}^{*}, t\right)}-1, \frac{1}{M\left(\omega^{*}, \omega_{1}^{*}, t\right)}-1\right) \leq 0,
\end{aligned}
$$

That is,

TRIANGULAR INTUITIONISTIC FUZZY METRIC SPACES

$$
\begin{equation*}
\psi\left(\frac{1}{M\left(\omega^{*}, \omega_{1}^{*}, t\right)}-1, \frac{1}{M\left(\omega^{*}, \omega_{1}^{*}, t\right)}-1,0,0, \frac{1}{M\left(\omega^{*}, \omega_{1}^{*}, t\right)}-1, \frac{1}{M\left(\omega^{*}, \omega_{1}^{*}, t\right)}-1\right) \leq 0 \tag{2.24}
\end{equation*}
$$

which contradicts $\left(\psi_{3}\right)$, if $\omega_{*} \neq \omega^{*}$. Hence point of coincidence of $G$ and $g$ is unique. Then, we proved that $\omega^{*}$ is the unique point of coincidence of $(F, f)$ and $(G, g)$. Now, if $(F, f)$ and $(G, g)$ are weakly compatible, from $F \omega=f \omega=\omega^{*}$ and $G \omega^{\prime}=g \omega^{\prime}=\omega^{*}$, we have $F \omega^{*}=$ $F(f \omega)=f(F \omega)=f \omega^{*}$ and $G \omega^{*}=G\left(g \omega^{\prime}\right)=g\left(G \omega^{\prime}\right)=g \omega^{*}$. Now, we prove that $F \omega^{*}=$ $f \omega^{*}=G \omega^{*}=g \omega^{*}$. If not, then $F \omega^{*} \neq G \omega^{*}$ and from (2.1), we have

$$
\begin{aligned}
& \psi\left(\frac{1}{M\left(F \omega^{*}, G \omega^{*}, t\right)}-1, \frac{1}{M\left(f \omega^{*}, g \omega^{*}, t\right)}-1, \frac{1}{M\left(f \omega^{*}, F \omega^{*}, t\right)}-1\right. \\
& \left.\frac{1}{M\left(g \omega^{*}, G \omega^{*}, t\right)}-1, \frac{1}{M\left(f \omega^{*}, G \omega^{*}, t\right)}-1, \frac{1}{M\left(F \omega^{*}, g \omega^{*}, t\right)}-1\right) \leq 0
\end{aligned}
$$

That is,

$$
\begin{equation*}
\psi\left(\frac{1}{M\left(F \omega^{*}, G \omega^{*}, t\right)}-1, \frac{1}{M\left(F \omega^{*}, G \omega^{*}, t\right)}-1,0,0, \frac{1}{M\left(F \omega^{*}, G \omega^{*}, t\right)}-1, \frac{1}{M\left(F \omega^{*}, G \omega^{*}, t\right)}-1\right) \leq 0 \tag{2.25}
\end{equation*}
$$

By property $\left(\psi_{3}\right)$, we deduce that $\frac{1}{M\left(F \omega^{*}, G \omega^{*}, t\right)}-1 \leq 0$ that is $M\left(F \omega^{*}, G \omega^{*}, t\right)=1$ and then our assumption that $F \omega^{*} \neq G \omega^{*}$ was wrong. Hence $F \omega^{*}=f \omega^{*}=G \omega^{*}=g \omega^{*}$. Finally, we show that $F \omega^{*}=f \omega^{*}=G \omega^{*}=g \omega^{*}=\omega^{*}$. Again, from (2.1) and using $F \omega^{*}=f \omega^{*}=$ $G \omega^{*}=g \omega^{*}$, we obtain that

$$
\begin{aligned}
& \psi\left(\frac{1}{M\left(F \omega, G \omega^{*}, t\right)}-1, \frac{1}{M\left(f \omega, g \omega^{*}, t\right)}-1, \frac{1}{M(f \omega, F \omega, t)}-1\right. \\
& \left.\frac{1}{M\left(g \omega^{*}, G \omega^{*}, t\right)}-1, \frac{1}{M\left(f \omega, G \omega^{*}, t\right)}-1, \frac{1}{M\left(F \omega, g \omega^{*}, t\right)}-1\right) \leq 0
\end{aligned}
$$

That is,

$$
\begin{equation*}
\psi\left(\frac{1}{M\left(\omega^{*}, G \omega^{*}, t\right)}-1, \frac{1}{M\left(\omega^{*}, G \omega^{*}, t\right)}-1,0,0, \frac{1}{M\left(\omega^{*}, G \omega^{*}, t\right)}-1, \frac{1}{M\left(\omega^{*}, G \omega^{*}, t\right)}-1\right) \leq 0 \tag{2.26}
\end{equation*}
$$

yielding thereby $\left(\right.$ due to $\left.\left(\psi_{3}\right)\right), \frac{1}{M\left(\omega^{*}, G \omega^{*}, t\right)}-1 \leq 0$ and so $M\left(\omega^{*}, G \omega^{*}, t\right)=1$, a contradiction if $\omega^{*} \neq G \omega^{*}$. Hence $F \omega^{*}=f \omega^{*}=G \omega^{*}=g \omega^{*}=\omega^{*}$. Then $\omega^{*}$ is the unique common fixedpoint of $F, f, g$ and $G$. The proof for the case in which $\overline{F(X)}$ is complete is similar and is therefore omitted. This completes the proof.

For mapping $G: X \rightarrow X$, we denote $\mathcal{F}(G)=\{\xi \in X: \xi=G \xi\}$.

Theorem: 2.2 Let $F, G, f$ and $g$ be four self-maps of a triangular intuitionistic fuzzy metric space satisfying the conditions (2.1) for all $\xi, \eta \in X$ and $t>0$, then

$$
\begin{equation*}
\mathcal{F}(F) \cap \mathcal{F}(f) \cap \mathcal{F}(g)=\mathcal{F}(G) \cap \mathcal{F}(f) \cap \mathcal{F}(g) \tag{2.27}
\end{equation*}
$$

Proof: Let $\omega^{*} \in \mathcal{F}(F) \cap \mathcal{F}(f) \cap \mathcal{F}(g)$. Then using (2.1), we have

$$
\begin{aligned}
& \psi\left(\frac{1}{M\left(F \omega^{*}, G \omega^{*}, t\right)}-1, \frac{1}{M\left(\mathrm{I} \omega^{*}, g \omega^{*}, t\right)}-1, \frac{1}{M\left(f \omega^{*}, F \omega^{*}, t\right)}-1\right. \\
& \left.\frac{1}{M\left(g \omega^{*}, G \omega^{*}, t\right)}-1, \frac{1}{M\left(f \omega^{*}, G \omega^{*}, t\right)}-1, \frac{1}{M\left(F \omega^{*}, g \omega^{*}, t\right)}-1\right) \leq 0
\end{aligned}
$$

That is,

$$
\psi\left(\frac{1}{M\left(\omega^{*}, G \omega^{*}, t\right)}-1,0,0, \frac{1}{M\left(\omega^{*}, G \omega^{*}, t\right)}-1, \frac{1}{M\left(\omega^{*}, G \omega^{*}, t\right)}-1,0\right) \leq 0,
$$

By property $\left(\psi_{2 a}\right)$, we deduce that

$$
\frac{1}{M\left(\omega^{*}, G \omega^{*}, t\right)}-1 \leq 0
$$

and so $M\left(\omega^{*}, G \omega^{*}, t\right)=1$, a contradiction if $M\left(\omega^{*}, G \omega^{*}, t\right)<1$. This means that $\omega^{*} \in$ $\mathcal{F}(G) \cap \mathcal{F}(f) \cap \mathcal{F}(g)$. Thus,

$$
\mathcal{F}(F) \cap \mathcal{F}(f) \cap \mathcal{F}(\mathrm{J}) \subset \mathcal{F}(G) \cap \mathcal{F}(f) \cap \mathcal{F}(g)
$$

Similarly, we can show that

$$
\mathcal{F}(G) \cap \mathcal{F}(f) \cap \mathcal{F}(g) \subset \mathcal{F}(F) \cap \mathcal{F}(f) \cap \mathcal{F}(g)
$$

Thus, it follows that

$$
\mathcal{F}(G) \cap \mathcal{F}(f) \cap \mathcal{F}(g)=\mathcal{F}(F) \cap \mathcal{F}(f) \cap \mathcal{F}(g)
$$

From Theorem 2.1, we can deduce a host of corollaries which are embodied in the following:
Corollary 2.3 The conclusions of Theorem 2.1 remain true if for all $\xi, \eta \in X ;(\xi \neq \eta)$ and $t>$ 0 , the implicit relation (2.1) is replaced by one of the following:

$$
\begin{gather*}
\frac{1}{M(F \xi, G \eta, t)}-1 \leq k \operatorname{ma\xi }\left\{\frac{1}{M(f \xi, g \eta, t)}-1, \frac{1}{M(f \xi, F \xi, t)}-1, \frac{1}{M(g \eta, G \eta, t)}-1,\right.  \tag{2.28}\\
\left.\frac{1}{2}\left[\left(\frac{1}{M(f \xi, G \eta, t)}-1\right)+\left(\frac{1}{M(F \xi, g \eta, t)}-1\right)\right]\right\}
\end{gather*}
$$

where $k \in(0,1)$.

$$
\begin{gather*}
\frac{1}{M(F \xi, G \eta, t)}-1 \leq k \operatorname{ma\xi }\left\{\frac{1}{M(f \xi, g \eta, t)}-1, \frac{1}{M(f \xi, F \xi, t)}-1, \frac{1}{M(g \eta, G \eta, t)}-1,\right.  \tag{2.29}\\
\left.\frac{1}{2}\left(\frac{1}{M(f \xi, G \eta, t)}-1\right), \frac{1}{2}\left(\frac{1}{M(F \xi, g \eta, t)}-1\right)\right\}
\end{gather*}
$$

where $k \in(0,1)$.

$$
\begin{gather*}
\frac{1}{M(F \xi, G \eta, t)}-1 \leq k \operatorname{ma\xi }\left\{\frac{1}{M(f \xi, g \eta, t)}-1, \frac{1}{2}\left[\left(\frac{1}{M(f \xi, F \xi, t)}-1\right)+\left(\frac{1}{M(g \eta, G \eta, t)}-1\right)\right]\right.  \tag{2.30}\\
\left.\frac{1}{2}\left[\left(\frac{1}{M(f \xi, G \eta, t)}-1\right)+\left(\frac{1}{M(F \xi, g \eta, t)}-1\right)\right]\right\},
\end{gather*}
$$

where $k \in(0,1)$

$$
\begin{gather*}
\frac{1}{M(F \xi, G \eta, t)}-1 \leq a\left(\frac{1}{M(I \xi, g \eta, t)}-1\right)+b\left(\frac{1}{M(f \xi, F \xi, t)}-1\right)+c\left(\frac{1}{M(g \eta, G \eta, t)}-1\right)  \tag{2.31}\\
+d\left(\frac{1}{M(f \xi, G \eta, t)}-1\right)+e\left(\frac{1}{M(F \xi, g \eta, t)}-1\right)
\end{gather*}
$$

where $a+b+c+d+e<1, d, e \geq 0$.

$$
\begin{gather*}
\frac{1}{M(F \xi, G \eta, t)}-1 \leq \frac{k}{2} \operatorname{ma\xi }\left\{\frac{1}{M(f \xi, g \eta, t)}-1, \frac{1}{M(f \xi, F \xi, t)}-1, \frac{1}{M(g \eta, G \eta, t)}-1, \frac{1}{M(f \xi, G \eta, t)}-1,\right.  \tag{2.32}\\
\left.\frac{1}{M(F \xi, g \eta, t)}-1\right\}
\end{gather*}
$$

where $k \in(0,1)$.

$$
\begin{gather*}
\frac{1}{M(F \xi, G \eta, t)}-1 \leq a\left(\frac{1}{M(f \xi, g \eta, t)}-1\right)+b\left(\frac{1}{M(f \xi, F \xi, t)}-1\right)+c\left(\frac{1}{M(g \eta, G \eta, t)}-1\right)  \tag{2.33}\\
+d\left[\left(\frac{1}{M(f \xi, G \eta, t)}-1\right)+\left(\frac{1}{M(F \xi, g \eta, t)}-1\right)\right]
\end{gather*}
$$

where $a+b+c+2 d<1, d \geq 0$.

$$
\begin{align*}
& \frac{1}{M(F \xi, G \eta, t)}-1 \leq \phi( \operatorname{ma\xi }\left\{\frac{1}{M(f \xi, g \eta, t)}-1, \frac{1}{M(f \xi, F \xi, t)}-1,\right.  \tag{2.34}\\
&\left.\left.\frac{1}{M(g \eta, G \eta, t)}-1, \frac{1}{2}\left[\left(\frac{1}{M(f \xi, G \eta, t)}-1\right)+\left(\frac{1}{M(F \xi, g \eta, t)}-1\right)\right]\right\}\right)
\end{align*}
$$

where $\phi: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$is an increasing upper semi-continuous function with $\phi(0)=0$ and $\phi(v)<v$ for each $v>0$.

$$
\begin{align*}
& \frac{1}{M(F \xi, G \eta, t)}-1 \leq \phi\left(\frac{1}{M(f \xi, g \eta, t)}-1,\right. \frac{1}{M(f \xi, F \xi, t)}-1, \frac{1}{M(g \eta, G \eta, t)}-1,  \tag{2.35}\\
&\left.\frac{1}{M(f \xi, G \eta, t)}-1, \frac{1}{M(F \xi, g \eta, t)}-1\right)
\end{align*}
$$

where $\phi: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$is an upper semi-continuous and non-decreasing function in each coordinate variable such that with $\phi(v, v, a v, b v, c v)<v$ for each $v>0$ and $a, b, c \geq 0$ with $a+b+c \leq 3$.

Setting $F=G$ and $f=g$ in Theorem 2.1, we get the following corresponding fixed-point theorem.

Corollary 2.4 Let $F$ and $g$ be two self-maps of a triangular intuitionistic fuzzy metric space $(X, M, N, *, \diamond)$ with $\overline{F(X)} \subseteq g(X)$ and for all $\xi, \eta \in X, t>0$ and some $\psi \in \Psi$,

$$
\begin{align*}
& \psi\left(\frac{1}{M(F \xi, F \eta, t)}-1, \frac{1}{M(g \xi, g \eta, t)}-1, \frac{1}{M(g \xi, F \xi, t)}-1,\right.  \tag{2.36}\\
& \left.\frac{1}{M(g \eta, F \eta, t)}-1, \frac{1}{M(g \xi, F \eta, t)}-1, \frac{1}{M(F \xi, g \eta, t)}-1\right) \leq 0,
\end{align*}
$$

If $\overline{F(X)}$ is a complete subspace of $X$, then $(F, g)$ has a unique point of coincidence in $X$. Moreover, if $(F, g)$ is weakly compatible, then $(F, g)$ has a unique common fixed-point in $X$.

Remark 2.5 A corollary similar to Corollary 2.4 can be outlined in respect of Corollary 2.3 yielding thereby a host of fixed-point theorems.

Setting $g=f_{X}$ (the identity mapping on $X$ ) in Corollary 2.1, we get the following corresponding fixed-point theorem.

Corollary 2.6 Let $F$ be a self-maps of a triangular intuitionistic fuzzy metric space ( $X, M, N$, *, $\diamond)$ such that for all $\xi, \eta \in X, t>0$ and some $\psi \in \Psi$,

$$
\begin{align*}
& \psi\left(\frac{1}{M(F \xi, F \eta, t)}-1, \frac{1}{M(\xi, \eta, t)}-1, \frac{1}{M(\xi, F \xi, t)}-1,\right.  \tag{2.37}\\
& \left.\frac{1}{M(\eta, F \eta, t)}-1, \frac{1}{M(\xi, F \eta, t)}-1, \frac{1}{M(F \xi, \eta, t)}-1\right) \leq 0,
\end{align*}
$$

If $\overline{F(X)}$ is a complete subspace of $X$, then S has a unique common fixed-point in $X$.
Remark 2.7 A corollary similar to Corollary 2.6 can be outlined in respect of Corollary 2.3 yielding thereby a host of fixed-point theorems.

TRIANGULAR INTUITIONISTIC FUZZY METRIC SPACES

## 3. ApPLICATION

As an application of Theorem 2.1, we prove a common fixed-point theorem for four finite families of mappings which runs as follows:

Theorem 3.1 Let $\left\{F_{1}, F_{2}, \ldots \ldots, F_{m}\right\},\left\{G_{1}, G_{2}, \ldots \ldots, G_{p}\right\}, \quad\left\{f_{1}, f_{2}, \ldots \ldots, f_{q}\right\}$ and $\left\{g_{1}, g_{2}, \ldots \ldots, g_{r}\right\}$ be four finite families of self-mappings of a triangular intuitionistic fuzzy metric space $(X, M, N, *, \diamond)$ with

$$
\begin{aligned}
& F=\prod_{i=1}^{m} F_{i}, G=\prod_{j=1}^{p} G_{j}, \\
& f=\prod_{k=1}^{q} f_{k}, g=\prod_{l=1}^{r} g_{l} .
\end{aligned}
$$

satisfying condition (2.1) of Theorem 2.1. Suppose that $\overline{G(X)} \subseteq f(X)$ and $\overline{F(X)} \subseteq g(X)$, wherein one of $\overline{G(X)}$ and $\overline{F(X)}$ is a complete subspace of $X$, then $(F, f)$ and $(G, g)$ have a point of coincidence in $X$.

Moreover, if

$$
\begin{aligned}
& F_{o} F_{r}=F_{r} F_{o}, f_{u} f_{v}=f_{v} f_{u} \\
& G_{s} G_{t}=G_{t} G_{s}, g_{e} g_{h}=g_{h} g_{e} \\
& F_{o} f_{u}=f_{u} F_{o}, G_{s} g_{e}=G_{s} g_{e}
\end{aligned}
$$

for all $o, r \in\{1,2, \ldots \ldots \ldots, m\}, u, v \in\{1,2, \ldots \ldots ., q\}, s, t \in\{1,2, \ldots \ldots ., p\}$, and $e, h \in$ $\{1,2, \ldots \ldots, r\}$, then for all $o \in\{1,2, \ldots \ldots, m\}, u \in\{1,2, \ldots \ldots \ldots, q\}, s \in\{1,2, \ldots \ldots, p\}$ and $\mathrm{e} \in\{1,2, \ldots \ldots, r\}, F_{o}, G_{s}, f_{u}$ and $g_{e}$ have a common fixed point.

Proof The conclusions " $(F, f)$ and $(G, g)$ have a point of coincidence in $X$ " are immediate as $F, G, f$ and $g$ satisfy all the conditions of theorem 2.1. In view of pairwise commutativity of various pairs of the families $(F, f)$ and $(G, g)$, the weak compatibility of pairs $(F, f)$ and $(G, g)$ are immediate. Thus all the conditions of theorem 2.1 (for mappings $F, G, f$ and $g$ ) are satisfied ensuring the existence of a unique common fixed point, say $\omega^{*}$. Now, one needs to show that $\omega^{*}$ remains the fixed-point of all the component maps. For this consider

$$
\begin{equation*}
F\left(F_{o} \omega^{*}\right)=\left(\prod_{i=1}^{m} F_{i}\right)\left(F_{o} \omega^{*}\right) \tag{3.1}
\end{equation*}
$$

$$
\begin{aligned}
& =\left(\prod_{i=1}^{m-1} F_{i}\right)\left(F_{m} F_{o}\right) \omega^{*} \\
& =\left(\prod_{i=1}^{m-1} F_{i}\right)\left(F_{m} F_{o} \omega^{*}\right) \\
& =\left(\prod_{i=1}^{m-2} F_{i}\right)\left(F_{m-1} F_{o}\left(F_{m} \omega^{*}\right)\right) \\
& =\left(\prod_{i=1}^{m-2} F_{i}\right)\left(F_{o} F_{m-1}\left(F_{m} \omega^{*}\right)\right) \\
& =\cdots \ldots \ldots \ldots \ldots \\
& =F_{1} F_{o}\left(\prod_{i=2}^{m} F_{i} \omega^{*}\right) \\
& =F_{o} F_{1}\left(\prod_{i=2}^{m} F_{i}\left(\omega^{*}\right)\right) \\
& =F_{o}\left(\prod_{i=1}^{m} F_{i}\left(\omega^{*}\right)\right) \\
& =F_{o}\left(F \omega^{*}\right)=F_{o} \omega^{*}
\end{aligned}
$$

Similarly, one can show that,

$$
\begin{align*}
& F\left(f_{u} \omega^{*}\right)=f_{u}\left(F \omega^{*}\right)=f_{u} \omega^{*},  \tag{3.2}\\
& f\left(f_{u} \omega^{*}\right)=f_{u}\left(f \omega^{*}\right)=f_{u} \omega^{*}, \\
& f\left(F_{o} \omega^{*}\right)=F_{o}\left(f \omega^{*}\right)=F_{o} \omega^{*}, \\
& G\left(G_{s} \omega^{*}\right)=G_{s}\left(G \omega^{*}\right)=G_{s} \omega^{*}, \\
& G\left(g_{e} \omega^{*}\right)=g_{e}\left(G \omega^{*}\right)=g_{e} \omega^{*}, \\
& g\left(g_{e} \omega^{*}\right)=g_{e}\left(g \omega^{*}\right)=g_{e} \omega^{*}, \\
& G\left(g_{e} \omega^{*}\right)=g_{e}\left(G \omega^{*}\right)=g_{e} \omega^{*} .
\end{align*}
$$

which show that (for all $o \in\{1,2,3, \ldots \ldots, m\}, u \in\{1,2, \ldots \ldots, q\}, s \in\{1,2, \ldots \ldots, p\}$ and $e \in$ $\{1,2, \ldots \ldots, r\}) F_{o} \omega^{*}$ and $f_{u} \omega^{*}$ are other fixed points of the pair $(F, f)$ whereas $G_{s} \omega^{*}$ and $g_{e} \omega^{*}$ are other fixed points of the pair $(G, g)$.

Now in view of uniqueness of the fixed-point $F, G, f$ and $g$ (for all $o \in\{1,2, \ldots, m\}, u \in$ $\{1,2, \ldots, q\}, s \in\{1,2, \ldots \ldots, p\}$ and $e \in\{1,2, \ldots ., r\})$, one can write $F_{o} \omega^{*}=f_{u} \omega^{*}=G_{s} \omega^{*}=$ $g_{e} \omega^{*}=\omega^{*}$.

This means that the point $\omega^{*}$ is a common fixed-point of $F_{o}, f_{u}, G_{s}$ and $g_{e}$. for all $o \in$ $\{1,2, \ldots \ldots m\}, u \in\{1,2, \ldots \ldots q\}, s \in\{1,2, \ldots \ldots p\}$ and $e \in\{1,2, \ldots \ldots . r\}$. By setting

TRIANGULAR INTUITIONISTIC FUZZY METRIC SPACES

$$
\begin{gather*}
F_{1}=F_{2}=\cdots=F_{m}=F,  \tag{3.3}\\
G_{1}=G_{2}=\cdots=G_{p}=G, \\
f_{1}=f_{2}=\cdots=f_{q}=f, \\
g_{1}=g_{2}=\cdots=g_{r}=g .
\end{gather*}
$$

One deduces the following corollary for various iterates of $F, G, f$ and $g$, which can also be viewed as partial generalization of theorem 2.1.

Corollary: 3.2 Let $(F, f)$ and $(G, g)$ be two commuting pairs of self-mappings of a triangular intuitionistic fuzzy metric space $(X, M, N, *, \diamond)$ with $\overline{G^{p}(X)} \subseteq f^{q}(X)$ and $\overline{F^{m}(X)} \subseteq g^{r}(X)$ and for all $\xi, \eta \in X, t>0$ and some $\psi \in \Psi$,

$$
\begin{align*}
& \psi\left(\frac{1}{M\left(F^{m} \xi, G^{p} \eta, t\right)}-1, \frac{1}{M\left(f^{q} \xi, g^{r} \eta, t\right)}-1, \frac{1}{M\left(f^{q} \xi, F^{m} \xi, t\right)}-1\right.  \tag{3.4}\\
& \left.\frac{1}{M\left(g^{r} \eta, G^{p} \eta, t\right)}-1, \frac{1}{M\left(f^{q} \xi, G^{p} \eta, t\right)}-1, \frac{1}{M\left(F^{m} \xi, g^{r} \eta, t\right)}-1\right) \leq 0
\end{align*}
$$

If one of $\overline{G^{p}(X)}$ and $\overline{F^{m}(X)}$ is a complete subspace of $X$, then $(F, f)$ and $(G, g)$ have a unique point of coincidence in $X$. Moreover, if $(F, f)$ and $(G, g)$ are weakly compatible, then $F, G, f$ and $g$ have a unique common fixed-point in $X$.

Theorem 3.3 Let $\left\{F_{1}, F_{2}, \ldots \ldots, F_{m}\right\}$ and $\left\{g_{1}, g_{2}, \ldots \ldots, g_{r}\right\}$ be two finite families of selfmappings of a triangular intuitionistic fuzzy metric space $(X, M, N, *, \diamond)$ with $F=$ $\prod_{i=1}^{m} F_{i}, g=\prod_{j=1}^{r} g_{j}$ satisfying condition (2.36) of Corollary 2.4. Suppose that $\overline{F(X)} \subseteq g(X)$, wherein $\overline{F(X)}$ is a complete subspace of $X$, then $(F, g)$ have a unique point of coincidence. Moreover, if $F_{p} F_{q}=F_{q} F_{p}, \quad g_{k} g_{l}=\mathrm{J}_{l} g_{k}$ and $F_{i} g_{k}=g_{k} F_{i}$ for all $p, q \in\{1,2, \ldots \ldots, m\}$ and $k, l \in\{1,2, \ldots \ldots, r\}$, then $(p \in\{1,2, \ldots \ldots, m\}$ and $k \in\{1,2, \ldots \ldots, p\}) F_{p}$ and $g_{k}$ have a common fixed-point in $X$.

Proof: The conclusion " $(F, g)$ has a point of coincidence" is immediate as $F$ and $g$ satisfies all the conditions of Corollary 2.4. Now appealing to component wise commutativity of various pairs, one can immediately assert that $F g=g F$ and hence, obviously the pair $(F, g)$ is
weakly compatible. Note that all the conditions (2.36) of Corollary 2.4 (for mappings $F$ and $g$ ) are satisfied ensuring the existence of unique common fixed point, say $\omega^{*}$. Now one need to show that $\omega^{*}$ remains the fixed-point of all the component mappings. For this consider

$$
\begin{align*}
F\left(F_{p} \omega^{*}\right) & =\left(\prod_{i=1}^{m} F_{i}\right)\left(F_{p} \omega^{*}\right)  \tag{3.5}\\
& =\left(\prod_{i=1}^{m-1} F_{i}\right)\left(F_{m} F_{p}\right) \omega^{*} \\
& =\left(\prod_{i=1}^{m-1} F_{i}\right)\left(F_{m} F_{p} \omega^{*}\right) \\
& =\left(\prod_{i=1}^{m-2} F_{i}\right)\left(F_{m-1} F_{p}\left(F_{m} \omega^{*}\right)\right) \\
& =\left(\prod_{i=1}^{m-2} F_{i}\right)\left(F_{p} F_{m-1}\left(F_{m} \omega^{*}\right)\right) \\
& =\cdots \ldots \ldots \ldots \ldots \ldots \\
& =F_{1} F_{p}\left(\prod_{i=2}^{m} F_{i} \omega^{*}\right) \\
& =F_{p} F_{1}\left(\prod_{i=2}^{m} F_{i}\left(\omega^{*}\right)\right) \\
& =F_{p}\left(\prod_{i=1}^{m} F_{i}\left(\omega^{*}\right)\right) \\
& =F_{p}\left(F \omega^{*}\right)=F_{p} \omega^{*}
\end{align*}
$$

Similarly, one can show that,

$$
\begin{align*}
& F\left(g_{k} \omega^{*}\right)=g_{k}\left(F \omega^{*}\right)=g_{k} \omega^{*},  \tag{2.43}\\
& g\left(g_{k} \omega^{*}\right)=g_{k}\left(g \omega^{*}\right)=g_{k} \omega^{*}, \\
& g\left(F_{p} \omega^{*}\right)=F_{p}\left(g \omega^{*}\right)=g_{p} \omega^{*},
\end{align*}
$$

which show that (for all $p \in\{1,2, \ldots ., m\}, k \in\{1,2, \ldots . . r\}$ ) $F_{p} \omega^{*}$ and $g_{k} \omega^{*}$ are other fixed points of the pair $(F, g)$.

Now in view of uniqueness of the fixed-point $F, G, f$ and $g$ (for all $p \in\{1,2, \ldots \ldots, m\}, k \in$ $\{1,2, \ldots \ldots, r\}$ ), one can write $F_{p} \omega^{*}=g_{k} \omega^{*}=\omega^{*}$.

This means that the point $\omega^{*}$ is a common fixed-point of $F_{p}$ and $g_{k}$. for all $p \in\{1,2, \ldots \ldots, m\}$, $k \in\{1,2, \ldots . ., r\}$. By setting

$$
\begin{equation*}
F_{1}=F_{2}=\cdots=F_{m}=F, \tag{2.44}
\end{equation*}
$$

TRIANGULAR INTUITIONISTIC FUZZY METRIC SPACES

$$
g_{1}=g_{2}=\cdots=g_{r}=g .
$$

One deduces the following corollary for various iterates of $F$ and $g$, which can also be viewed as partial generalization of Corollary 2.1.

Corollary: 3.4 Let $(F, g)$ be two commuting pairs of self-mappings of a triangular intuitionistic fuzzy metric space $(X, M, N, *, \diamond)$ with $\overline{F^{m}(X)} \subseteq g^{r}(X)$ and for all $\xi, \eta \in X, t>0$ and some $\psi \in \Psi$,

$$
\begin{align*}
& \psi\left(\frac{1}{M\left(F^{m} \xi, F^{m} \eta, t\right)}-1, \frac{1}{M\left(g^{r} \xi, g^{r} \eta, t\right)}-1, \frac{1}{M\left(g^{r} \xi, F^{m} \xi, t\right)}-1\right.  \tag{2.45}\\
& \left.\frac{1}{M\left(g^{r} y, F^{m} \eta, t\right)}-1, \frac{1}{M\left(g^{r} \xi, F^{m} \eta, t\right)}-1, \frac{1}{M\left(F^{m} \xi, g^{r} \eta, t\right)}-1\right) \leq 0
\end{align*}
$$

Assume that $\overline{F^{m}(X)}$ is a complete subspace of $X$, then $(F, g)$ has a unique point of coincidence in X. Moreover, if $(F, g)$ is weakly compatible, then $(F, g)$ has a unique common fixed-point in $X$.

## 4. EXAMPLE

Now we furnish an example to demonstrate the validity of the hypotheses of generality of our result.

Example 4.1 Let $X=\{0,1,3,4\}$ be a set with usual metric. Define intuitionistic fuzzy metric by

$$
M(\xi, \eta, t)=\frac{1}{1+|\xi-\eta|}, \quad N(\xi, \eta, t)=\frac{|\xi-\eta|}{1+|\xi-\eta|},
$$

where

$$
a * b=\min \{a, b\} \text { and } \quad a \diamond b=\operatorname{ma\xi }\{a, b\} .
$$

Also define the mappings $F, G, f, g: X \rightarrow X$ by

$$
\begin{aligned}
F \xi & =1, \quad \forall \xi \in X, \\
G \xi & =\left\{\begin{array}{lr}
0, & \xi \in\{3\} \\
1, & \xi \in\{0,1,2\} .
\end{array}\right.
\end{aligned}
$$

and

$$
f \xi=g \xi=\xi, \forall \xi \in X
$$

that is, $f=g=f_{X}$ (the identity mapping on $X$ ). We can see that the mappings $(F, f)$ and $(G, \mathrm{~J})$
are commute at 1 which is their coincidence point. Obviously, $(F, f)$ and $(G, g)$ are weakly compatible.

Also $F(X)=\{1\}, G(X)=\{0,1\}$ and $f(X)=F(X)=\{0,1,3,4\}$. Clearly, $\overline{F(X)}=\{1\} \subset$ $\{0,1,3,4\}=g(X)$ and $\overline{G(X)}=\{0,1\} \subset\{0,1,3,4\}=f(X)$ are complete subspace of $X$.

Now, we define $\psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right): \mathbb{R}_{+}^{6} \rightarrow \mathbb{R}$ as:

$$
\begin{aligned}
& \psi\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right) \\
& \quad=u_{1}-a_{1}\left(\frac{u_{3}^{2}+u_{4}^{2}}{u_{3}+u_{4}}\right)-a_{2} u_{2}-a_{3}\left(u_{5}+u_{6}\right)
\end{aligned}
$$

where $a_{i} \geq 0$ with at least one $a_{i}$ non-zero and $a_{1}+a_{2}+2 a_{3}<1$.
Now taking $a_{1}=\frac{1}{5}, a_{2}=a_{3}=\frac{1}{4}$, we consider the following cases.
(1). Let $\xi=0$ and $\eta=1$. Then,

$$
\begin{aligned}
& \psi\left(\frac{1}{M(F 0, G 1, t)}-1, \frac{1}{M(f 1, g 0, t)}-1, \frac{1}{M(f 0, F 0, t)}-1, \frac{1}{M(g 1, G 1, t)}-1, \frac{1}{M(f 0, G 1, t)}-1, \frac{1}{M(F 0, g 1, t)}-1\right) \\
& \quad=\psi\left(\frac{1}{M(1,1, t)}-1, \frac{1}{M(1,0, t)}-1, \frac{1}{M(0,1, t)}-1, \frac{1}{M(1,1, t)}-1, \frac{1}{M(0,1, t)}-1, \frac{1}{M(1,1, t)}-1\right) \\
& \quad=\psi(0,1,1,0,1,1) \\
& \quad=0-a_{1}\left(\frac{1+0}{1+0}\right)-a_{2} 1-a_{3}(1+1) \\
& \quad=\frac{-19}{20}<0 .
\end{aligned}
$$

(2). Let $\xi=0$ and $\eta=3$ Then,

$$
\begin{aligned}
& \psi\left(\frac{1}{M(F 0, G 3, t)}-1, \frac{1}{M(f 0, g 3, t)}-1, \frac{1}{M(f 0, F 0, t)}-1, \frac{1}{M(g 3, G 3, t)}-1, \frac{1}{M(f 0, G 3, t)}-1, \frac{1}{M(F 0, g 3, t)}-1\right) \\
& \quad=\psi\left(\frac{1}{M(1,0, t)}-1, \frac{1}{M(0,3, t)}-1, \frac{1}{M(0,1, t)}-1, \frac{1}{M(3,0, t)}-1, \frac{1}{M(0,0, t)}-1, \frac{1}{M(1,3, t)}-1\right) \\
& \quad=\psi(1,3,1,3,0,2) \\
& \quad=1-a_{1}\left(\frac{1+9}{1+3}\right)-3 a_{2}-a_{3}(0+2) \\
& \quad=\frac{-1}{2}<0 .
\end{aligned}
$$

(3). Let $\xi=0$ and $\eta=4$. Then,

$$
\begin{aligned}
& \psi\left(\frac{1}{M(F 0, G 4, t)}-1, \frac{1}{M(f 0, g 4, t)}-1, \frac{1}{M(f 0, F 0, t)}-1, \frac{1}{M(g 4, G 4, t)}-1, \frac{1}{M(f 0, G 4, t)}-1, \frac{1}{M(F 0, g 4, t)}-1\right) \\
& \quad=\psi\left(\frac{1}{M(1,1, t)}-1, \frac{1}{M(0,4, t)}-1, \frac{1}{M(0,1, t)}-1, \frac{1}{M(4,1, t)}-1, \frac{1}{M(0,1, t)}-1, \frac{1}{M(1,4, t)}-1\right) \\
& \quad=\psi(0,4,1,3,1,3) \\
& \quad=0-a_{1}\left(\frac{1+9}{1+3}\right)-4 a_{2}-a_{3}(1+3) \\
& \quad=\frac{-5}{2}<0 .
\end{aligned}
$$

(4). Let $\xi=1$ and $\eta=3$. Then,

$$
\begin{aligned}
& \psi\left(\frac{1}{M(F 1, G 3, t)}-1, \frac{1}{M(f 1, g 3, t)}-1, \frac{1}{M(f 1, F 1, t)}-1, \frac{1}{M(g 3, G 3, t)}-1, \frac{1}{M(f 1, G 3, t)}-1, \frac{1}{M(F 1, g 3, t)}-1\right) \\
& \quad=\psi\left(\frac{1}{M(1,0, t)}-1, \frac{1}{M(1,3, t)}-1, \frac{1}{M(1,1, t)}-1, \frac{1}{M(3,0, t)}-1, \frac{1}{M(1,0, t)}-1, \frac{1}{M(1,3, t)}-1\right) \\
& \quad=\psi(1,2,0,3,1,2) \\
& \quad=1-a_{1}\left(\frac{0+9}{0+3}\right)-a_{2} 2-a_{3}(1+2) \\
& \quad=\frac{-17}{20}<0 .
\end{aligned}
$$

(5). Let $\xi=1$ and $\eta=4$. Then,

$$
\begin{aligned}
& \psi\left(\frac{1}{M(F 1, G 4, t)}-1, \frac{1}{M(f 1, g 4, t)}-1, \frac{1}{M(f 1, F 1, t)}-1, \frac{1}{M(g 4, G 4, t)}-1, \frac{1}{M(f 1 G 4, t)}-1, \frac{1}{M(F 1, g 4, t)}-1\right) \\
& \quad=\psi\left(\frac{1}{M(1,1, t)}-1, \frac{1}{M(1,4, t)}-1, \frac{1}{M(1,1, t)}-1, \frac{1}{M(4,1, t)}-1, \frac{1}{M(1,1, t)}-1, \frac{1}{M(1,4, t)}-1\right) \\
& \quad=\psi(0,3,0,3,0,3) \\
& \quad=0-a_{1}\left(\frac{0+9}{0+3}\right)-3 a_{2}-a_{3}(0+3) \\
& \quad=\frac{-21}{10}<0 .
\end{aligned}
$$

(6). Let $\xi=3$ and $\eta=4$. Then,

$$
\begin{aligned}
& \psi\left(\frac{1}{M(F 3, G 4, t)}-1, \frac{1}{M(f 3, g 4, t)}-1, \frac{1}{M(f 3, F 3, t)}-1, \frac{1}{M(g 4, G 4, t)}-1, \frac{1}{M(f 3, G 4, t)}-1, \frac{1}{M(F 3, g 4, t)}-1\right) \\
& \quad=\psi\left(\frac{1}{M(1,1, t)}-1, \frac{1}{M(3,4, t)}-1, \frac{1}{M(3,1, t)}-1, \frac{1}{M(4,1, t)}-1, \frac{1}{M(3,1, t)}-1, \frac{1}{M(3,4, t)}-1\right)
\end{aligned}
$$

$$
\begin{aligned}
& =\psi(0,1,3,4,3,1) \\
& =0-a_{1}\left(\frac{9+16}{3+4}\right)-a_{2}-\mathrm{a}_{3}(3+1) \\
& =\frac{-55}{28}<0 .
\end{aligned}
$$

Therefore, all condition of Theorem 2.1 hold and $\mathrm{S}, \mathrm{T}, \mathrm{I}$ and J have a unique common fixedpoint $\left(\omega^{*}=1\right)$.

## AUTHOR's CONTRIBUTIONS

Both authors contributed equally and significantly to writing this paper. Both authors read and approved the final manuscript.

## CONFLICT OF INTERESTS

The authors declare that there is no conflict of interests.

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## SHRUTI EKTARE, AMIT KUMAR PANDEY

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[^0]:    *Corresponding author
    E-mail address: shrutiphd2021@gmail.com
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