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THE CLASS Φ_{α} OF AUXILIARY FUNCTIONS AND FIXED POINT IN G-METRIC **SPACE**

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Abstract. Some generalizations of the fixed point theorems of Mohanta [1], Mustafa and Sims [2] and of Vats et

al [7] are proved, under a new class Φ_{α} of auxiliary functions. Also, G-contractive fixed points are obtained for

some contraction type conditions.

Keywords: G-complete metric space; the class Φ_{α} ; fixed point; G-contractive fixed point

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1. Introduction

Several fixed point theorems in metric space setting have been proved through contraction type

conditions involving different types of auxiliary functions. One such auxiliary function is a

mapping $\psi:[0,\infty)\to[0,\infty)$, known as a contractive modulus, with the choice

(1.1)

 $\psi(0) = 0$ and $\psi(t) < t$ for t > 0.

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The notion of contractive modulus was introduced by Solomon Leader [6]. For instance,

(1.2)
$$\psi_1(t) = \frac{t}{t+1} \text{ and } \psi_2(t) = \frac{t^2}{t+1}$$

are contractive moduli. We denote by Ψ , the class of all contractive moduli.

Given a positive integer α , we introduce a generalized class Φ_{α} as follows:

(1.3)
$$\Phi_{\alpha} = \{ \phi : [0, \infty) \to [0, \infty) | \phi(0) = 0, \phi(\alpha t) < t \text{ for } t > 0 \}.$$

Remark 1.1. It is obvious that, for $\alpha = 1$, Φ_{α} reduces to the class Ψ . That is $\Phi_1 = \Psi$. However, in general a contractive modulus need not belong to Φ_{α} for $\alpha > 1$, as shown in the following example:

Example 1.1. Consider

$$\psi(t) = \begin{cases} \frac{2t}{3}, & t < 1\\ \frac{t}{2}, & t \ge 1 \end{cases}$$

Obviously, $\psi(0) = 0$ and $\psi(t) < t$ for all t > 0 so that $\psi \in \Psi$. But

$$\psi(2t) = \begin{cases} \frac{4t}{3}, & t < 1/2 \\ t, & t \ge 1/2 \end{cases}$$

so that $\psi(2t) \ge t$ for all t > 0. Thus $\psi \notin \Phi_{\alpha}$.

Definition 1.1. A mapping $\phi \in \Phi_{\alpha}$ is said to be upper semicontinuous at $t_0 \ge 0$ if $\limsup_{n \to \infty} \phi(t_n) \le \phi(t_0)$ whenever $\langle t_n \rangle_{n=1}^{\infty}$ is such that $\lim_{n \to \infty} t_n = t_0$, and ϕ is u.s.c if it is u.s.c. at every $t \ge 0$.

Example 1.2. Mappings

(1.4)
$$\frac{t}{t+1}, \frac{t^2}{t+1}, \phi(t) = \begin{cases} qt & (0 \le t \le 1) \\ t - q & (t > 1), \end{cases}$$

and qt with $0 \le q < 1$, are continuous contractive modulii, while the contractive modulus

(1.5)
$$\psi(t) = \begin{cases} 0 & (0 \le t \le a) \\ t - a & (t > a) \end{cases}$$

with a > 0, is usc but not continuous.

In this paper, we obtain the fixed points of self-maps satisfying some contraction type conditions in terms of $\phi \in \Phi_{\alpha}$ for different choices of α in *G*-metric space. Also, we obtain *G*-contractive fixed points for some contraction type conditions (See Section 4).

2. G-metric space

Let *X* be a nonempty set and $G: X \times X \times X \to [0, \infty)$ such that

- (G1) G(x,y,z) = 0 whenever $x,y,z \in X$ are such that x = y = z,
- (G2) G(x,x,y) > 0 for all $x,y \in X$ with $x \neq y$,
- (G3) $G(x,x,y) \le G(x,y,z)$ for all $x,y,z \in X$ with $z \ne y$,
- (G4) $G(x,y,z) = G(\pi(x,y,z))$ for all $x,y,z \in X$, where $\pi(x,y,z)$ is a permutation on the set $\{x,y,z\}$

(G5)
$$G(x, y, z) \le G(x, w, w) + G(w, y, z)$$
 for all $x, y, z, w \in X$

Then G is called a G-metric on X and the pair (X,G), a G-metric space. Axiom (G5) is usually referred to as the rectangle inequality (of the G-metric G). This notion was introduced by Mustafa and Sims [2] in 2006.

In any G-metric space (X, G), we have

$$(2.1) G(x,y,y) \le 2G(x,x,y) \text{ for all } x,y \in X.$$

A G-metric space (X, G) is said to be symmetric if

$$(2.2) G(x,y,y) = G(x,x,y) ext{ for all } x,y \in X.$$

We use the following notions from of [2] in this paper:

Definition 2.1. Let (X,G) be a G-metric space. A G-ball in X is defined by

$$B_G(x,r) = \{ y \in X : G(x,y,y) < r \}.$$

It is easy to see that the family of all G-balls forms a base topology, called the G-metric topology $\tau(G)$ on X.

Also

(2.3)
$$\rho_G(x,y) = G(x,y,y) + G(x,x,y) \text{ for all } x,y \in X.$$

induces a metric on X, and the G-metric topology coincides with the metric topology induced by the metric ρ_G . This allows us to readily transform many concepts from metric space into the setting of G-metric space.

Definition 2.2. A sequence $\langle x_n \rangle_{n=1}^{\infty}$ in a *G*-metric space (X,G) is said to be *G-convergent* with limit $p \in X$ if it converges to p in the *G*-metric topology $\tau(G)$.

Definition 2.3. A sequence $\langle x_n \rangle_{n=1}^{\infty}$ in a *G*-metric space (X,G) is said to be *G*-Cauchy if $\lim_{n,m\to\infty} G(x_n,x_m,x_m)=0$.

Definition 2.4. A G-metric space (X,G) is said to be G-complete if every G-Cauchy sequence in X converges in it.

3. Fixed point theorems involving the class Φ_{α}

Our first result is

Theorem 3.1. Suppose that (X,G) is a complete G-metric space and f, a self-map on X satisfying the condition

where $\phi \in \Phi_2$ is nondecreasing and upper semicontinuous. Then f will have a unique fixed point p.

Proof. Let $x_0 \in X$ be arbitrary. Define $\langle x_n \rangle_{n=1}^{\infty} \subset X$ by

(3.2)
$$x_n = fx_{n-1} \text{ for } n \ge 1.$$

Writing with $x = x_{n-1}$ and $y = z = x_n$ in (3.1) and then using (2.1), we get

$$\begin{split} G(fx_{n-1},fx_n,fx_n) &= G(x_n,x_{n+1},x_{n+1}) \\ &\leq \phi \left(\max \left\{ G(x_{n-1},x_n,x_n), G(x_{n-1},fx_{n-1},fx_{n-1}), G(x_n,fx_n,fx_n), \right. \right. \\ & \left. G(x_n,fx_n,fx_n), G(x_{n-1},fx_n,fx_n), G(x_n,fx_n,fx_n), \right. \\ & \left. G(x_n,fx_{n-1},fx_{n-1}) \right\} \right) \\ &\leq \phi \left(\max \left\{ G(x_{n-1},x_n,x_n), G(x_{n-1},x_n,x_n), G(x_n,x_{n+1},x_{n+1}), \right. \right. \\ & \left. G(x_n,x_{n+1},x_{n+1}), G(x_{n-1},x_{n+1},x_{n+1}), \right. \\ & \left. G(x_n,x_{n+1},x_{n+1}), G(x_n,x_n,x_n) \right\} \right) \\ &\leq \phi \left(\max \left\{ G(x_{n-1},x_n,x_n), G(x_n,x_{n+1},x_{n+1}), G(x_{n-1},x_{n+1},x_{n+1}) \right\} \right) \\ &\leq \phi \left(\max \left\{ G(x_{n-1},x_n,x_n), G(x_n,x_{n+1},x_{n+1}), G(x_n,x_{n+1},x_{n+1}) \right\} \right) \\ &\leq \phi \left(G(x_{n-1},x_n,x_n) + G(x_n,x_{n+1},x_{n+1}) \right) \end{split}$$

Define

(3.3)
$$t_n = G(x_{n-1}, x_n, x_n) \text{ for } n \ge 1.$$

Then the above inequality can be written as

$$(3.4) t_{n+1} \le \phi\left(t_n + t_{n+1}\right)$$

We now prove that

(3.5)
$$t_n \ge t_{n+1} \text{ for } n \ge 1.$$

If possible, suppose that $t_m < t_{m+1}$ for some $m \ge 1$. Then $t_{m+1} > 0$. Since ϕ is nondecreasing, from (3.4) it follows that

$$t_{m+1} \leq \phi(t_{m+1} + t_m) < t_{m+1},$$

which is a contradiction. This proves (3.5). In other words, $\langle t_n \rangle_{n=1}^{\infty}$ is a decreasing sequence of nonnegative real numbers and hence converges to some $t \ge 0$.

Now using (3.5) in (3.4), we get

$$t_{n+1} \le \phi(t_{n+1} + t_n) \le \phi(2t_n) \text{ for } n \ge 1.$$

Taking the limit superior as $n \to \infty$ in this and then using the upper semicontinuity of ϕ , we obtain that

$$(3.6) t \le \phi(2t).$$

If t > 0 in (3.6), then the choice of ϕ implies that $t \le \phi(2t) < t$, which is a contradiction. Thus

(3.7)
$$t = \lim_{n \to \infty} t_n = \lim_{n \to \infty} G(x_{n-1}, x_n, x_n) = 0.$$

We now prove that $\langle x_n \rangle_{n=1}^{\infty}$ is a *G*-Cauchy sequence in *X*.

If possible we suppose that $\langle x_n \rangle_{n=1}^{\infty}$ is not *G*-Cauchy. Then for some $\varepsilon > 0$, we choose sequences $\langle x_{m_k} \rangle_{k=1}^{\infty}$ and $\langle x_{m_k} \rangle_{k=1}^{\infty}$ of positive integers such that $m_k > n_k > k$ and

(3.8)
$$G(x_{m_k}, x_{n_k}, x_{n_k}) \ge \varepsilon \text{ for } k = 1, 2, 3,$$

Suppose that m_k is the smallest integer exceeding n_k which satisfies (3.8). That is

$$(3.9) G(x_{m_k-1}, x_{n_k}, x_{n_k}) < \varepsilon.$$

Now by rectangle inequality of G, we see that

(3.10)
$$\varepsilon \leq G(x_{m_k}, x_{n_k}, x_{n_k}) \leq G(x_{m_k}, x_{m_k-1}, x_{m_k-1}) + G(x_{m_k-1}, x_{n_k}, x_{n_k})$$
$$< G(x_{m_k}, x_{m_k-1}, x_{m_k-1}) + \varepsilon$$

and from (3.7), we see that

(3.11)
$$\lim_{k \to \infty} G(x_{m_k - 1}, x_{m_k}, x_{m_k}) = 0$$

and

(3.12)
$$\lim_{k \to \infty} G(x_{n_k - 1}, x_{n_k}, x_{n_k}) = 0$$

Using (3.11) in (3.10), we get

(3.13)
$$\lim_{k\to\infty} G(x_{m_k}, x_{n_k}, x_{n_k}) = \varepsilon.$$

Also by rectangle inequality of G and (2.1), we get

$$G(x_{n_k-1}, x_{m_k}, x_{m_k}) \le G(x_{n_k-1}, x_{n_k}, x_{n_k}) + G(x_{n_k}, x_{m_k}, x_{m_k})$$

$$\le G(x_{n_k-1}, x_{n_k}, x_{n_k}) + 2G(x_{n_k}, x_{n_k}, x_{m_k}).$$

As $k \to \infty$ this in view of (3.12) and (3.13), gives

$$\lim_{k\to\infty}G(x_{n_k-1},x_{m_k},x_{m_k})=2\varepsilon.$$

On the other hand, writing $x = x_{m_k-1}$, $y = z = x_{n_k-1}$ in (3.1), we have

$$\begin{split} G(fx_{m_k-1},fx_{n_k-1},fx_{n_k-1}) &= G(x_{m_k},x_{n_k},x_{n_k}) \\ &\leq \phi \left(\max \left\{ G(x_{m_k-1},x_{n_k-1},x_{n_k-1}), G(x_{m_k-1},fx_{m_k-1},fx_{m_k-1}), \right. \right. \\ & \left. G(x_{n_k-1},fx_{n_k-1},fx_{n_k-1}), G(x_{n_k-1},fx_{n_k-1},fx_{n_k-1}), \right. \\ & \left. G(x_{m_k-1},fx_{n_k-1},fx_{n_k-1}), G(x_{n_k-1},fx_{n_k-1},fx_{n_k-1}), \right. \\ & \left. G(x_{n_k-1},fx_{m_k-1},fx_{m_k-1},fx_{m_k-1}) \right\} \right), \end{split}$$

or

$$\varepsilon \leq G(x_{m_{k}}, x_{n_{k}}, x_{n_{k}})$$

$$\leq \phi \left(\max \left\{ G(x_{m_{k}-1}, x_{n_{k}-1}, x_{n_{k}-1}), G(x_{m_{k}-1}, x_{m_{k}}, x_{m_{k}}), G(x_{n_{k}-1}, x_{n_{k}}, x_{n_{k}}), G(x_{n_{k}-1}, x_{n_{k}}, x_{n_{k}}), G(x_{n_{k}-1}, x_{n_{k}}, x_{n_{k}}), G(x_{n_{k}-1}, x_{n_{k}}, x_{n_{k}}), G(x_{n_{k}-1}, x_{n_{k}}, x_{n_{k}}) \right\} \right)$$

$$= \phi \left(\max \left\{ G(x_{m_{k}-1}, x_{n_{k}-1}, x_{n_{k}-1}), G(x_{m_{k}-1}, x_{m_{k}}, x_{m_{k}}), G(x_{n_{k}-1}, x_{n_{k}}, x_{n_{k}}), G(x_{n_{k}-1}, x_{n_{k}}, x_{n_{k}}), G(x_{n_{k}-1}, x_{n_{k}}, x_{n_{k}}) \right\} \right).$$

$$(3.15)$$

Proceeding the limit as $n \to \infty$ in (3.15) and then using upper semicontinuity of ϕ , (3.9), (3.11), (3.12),(3.13) and (3.14) we get

$$\varepsilon \le \phi \left(\max \left\{ \varepsilon, 0, 0, \varepsilon, 2\varepsilon \right\} \right) = \phi(2\varepsilon).$$

Since ϕ is nondecreasing, this finally gives

$$(3.16) \varepsilon \leq \phi(2\varepsilon) < \varepsilon,$$

which is a contradiction. Hence $\langle x_n \rangle_{n=1}^{\infty}$ must be a *G*-Cauchy sequence in *X*.

Since (X,G) is G-Complete, there exists a point $p \in X$ such that $\langle x_n \rangle_{n=1}^{\infty}$ is G-convergent to p. That is

$$\lim_{n \to \infty} x_{n-1} = \lim_{n \to \infty} x_n = p.$$

We now establish that p is a fixed point of f. In fact, writing $x = x_{n-1}$ and y = z = p in (3.1)

$$G(fx_{n-1}, fp, fp) = G(x_n, fp, fp)$$

$$\leq \phi \left(\max \left\{ G(x_{n-1}, p, p), G(x_{n-1}, fx_{n-1}, fx_{n-1}), G(p, fp, fp), G(p, fp, fp), G(p, fp, fp), G(p, fp, fp), G(p, fx_{n-1}, fx_{n-1}) \right\} \right)$$

$$\leq \phi \left(\max \left\{ G(x_{n-1}, p, p), G(x_{n-1}, x_n, x_n), G(p, fp, fp), G(p, fp, f$$

Proceeding the limit as $n \to \infty$ in (3.18) and then using (3.17), we get

$$G(p, fp, fp) \le \phi \left(\max \left\{ 0, 0, G(p, fp, fp), G(p, fp, fp), 0 \right\} \right)$$

$$= \phi \left(G(p, fp, fp) \right).$$

If $p \neq fp$, then G(p, fp, fp) > 0. Since ϕ is nondecreasing, (3.19) gives

$$0 < G(p,fp,fp) \leq \phi(G(p,fp,fp)) < G(p,fp,fp),$$

which is a contradiction. Hence p = fp.

To establish the uniqueness of the fixed point, we suppose that p and q are fixed points of f with $p \neq q$. Then Writing x = p and y = z = q in (3.1), we get

$$G(fp,fq,fq) \le \phi \left(\max \left\{ G(p,q,q), G(p,fp,fp), G(q,fq,fq), G(q,fq,fq), G(p,fq,fq), G(q,fq,fq), G(q,fq,fq), G(q,fp,fp) \right\} \right)$$

which on using (2.1) implies that

$$\begin{split} G(p,q,q) & \leq \phi \left(\max \left\{ G(p,q,q), 0, 0, 0, G(p,q,q), 0, G(q,p,p) \right\} \right) \\ & \leq \phi \left(\max \left\{ G(p,q,q), 2G(p,q,q) \right\} \right) \\ & = \phi (2G(p,q,q)). \end{split}$$

Since ϕ is nondecreasing, this gives

$$G(p,q,q) \le \phi(2G(p,q,q)) < G(p,q,q),$$

which is again a contradiction. Therefore, p = q.

Remark 3.1. Set $\phi(t) = kt$ for all $t \ge 0$, where 0 < k < 1/2 in Theorem 3.1. Then $\phi(0) = 0$ and $\phi(2t) = 2kt < t$ for all t > 0. Therefore, we get

Corollary 3.1 (Theorem 2.1, [3]). Suppose that (X,G) is a complete G-metric space and f, a self-map on X satisfying the condition

$$G(fx, fy, fz) \le k \max \left\{ G(x, y, z), G(x, fx, fx), G(y, fy, fy), G(z, fz, fz), G(x, fy, fy), G(y, fz, fz), G(z, fx, fx) \right\}$$

$$(3.20) \qquad \qquad for all \ x, y, z \in X,$$

where 0 < k < 1/2. Then f will have a unique fixed point p.

Just similar to Theorem 3.1, we can prove

Theorem 3.2. Suppose that (X,G) is a complete G-metric space and f, a self-map on X satisfying the condition

$$G(fx, fy, fz) \leq \phi \left(\max \left\{ G(x, fx, fx), G(x, fy, fy), \right. \right.$$

$$G(x, fz, fz), G(y, fy, fy), G(y, fx, fx),$$

$$G(y, fz, fz), G(z, fz, fz), G(z, fx, fx),$$

$$G(z, fy, fy) \right\} \right) for all x, y, z \in X,$$

$$(3.21)$$

where $\phi \in \Phi_2$ is nondecreasing and upper semicontinuous. Then f will have a unique fixed point p.

Remark 3.2. Set $\phi(t) = kt$ for all $t \ge 0$, where 0 < k < 1/2 in Theorem 3.2. Then $\phi(0) = 0$ and $\phi(2t) = 2kt < t$ for all t > 0. Therefore, we get

Corollary 3.2 (Theorem 1, [7]). Suppose that (X,G) is a complete G-metric space and f, a self-map on X satisfying the condition

$$G(fx, fy, fz) \le k \max \left\{ G(x, fx, fx), G(x, fy, fy), G(x, fy, fy), G(x, fz, fz), G(x, fz, fz), G(x, fx, fx), G(x, fz, fz), G(x, fz, fz), G(x, fx, fx), G(x, fy, fy) \right\}$$

$$G(x, fy, fy) \left\{ for \ all \ x, y, z \in X, \right\}$$

$$(3.22)$$

where 0 < k < 1/2. Then f will have a unique fixed point p.

With an argument, similar to that of Theorem 3.1, we can prove the following:

Theorem 3.3. Suppose that (X,G) is a complete G-metric space and f, a self-map on X satisfying the condition

$$G(fx, fy, fz) \le \phi \left(\max \left\{ G(x, fy, fy) + G(y, fx, fx) + G(z, fz, fz), \right. \right.$$

$$G(y, fz, fz) + G(z, fy, fy) + G(x, fx, fx),$$

$$G(z, fx, fx) + G(x, fz, fz) + G(y, fy, fy) \right\} \right)$$

$$(3.23)$$

$$for all x, y, z \in X,$$

where $\phi \in \Phi_3$ is nondecreasing and upper semicontinuous. Then f will have a unique fixed point p.

Remark 3.3. Set $\phi(t) = kt$ for all $t \ge 0$, where 0 < k < 1/3 in Theorem 3.3. Then $\phi(0) = 0$ and $\phi(3t) = 3kt < t$ for t > 0. Therefore, we have

Corollary 3.3 (Theorem 3.9, [1]). Suppose that (X,G) is a complete G-metric space and f, a self-map on X satisfying the condition

$$G(fx, fy, fz) \le k \max \left\{ G(x, fy, fy) + G(y, fx, fx) + G(z, fz, fz), \right.$$

$$G(y, fz, fz) + G(z, fy, fy) + G(x, fx, fx),$$

$$G(z, fx, fx) + G(x, fz, fz) + G(y, fy, fy) \right\}$$

$$for all x, y, z \in X,$$

where 0 < k < 1/3. Then f will have a unique fixed point p.

The fourth main result is given below without proof:

Theorem 3.4. Suppose that (X,G) is a complete G-metric space and f, a self-map on X satisfying the condition

$$G(fx, fy, fz) \le \phi \left(\max \left\{ G(x, fx, fx) + G(y, fy, fy) + G(z, fz, fz), \right. \right.$$

$$G(x, fy, fy) + G(y, fx, fx) + G(z, fy, fy),$$

$$G(x, fz, fz) + G(y, fz, fz) + G(z, fx, fx) \right\} \right)$$

$$(3.25)$$

$$for all x, y, z \in X,$$

where $\phi \in \Phi_4$ is nondecreasing upper semicontinuous. Then f will have a unique fixed point p.

Remark 3.4. Set $\phi(t) = kt$ for all $t \ge 0$, where 0 < k < 1/4 in Theorem 3.4. Then $\phi(0) = 0$ and $\phi(4t) = 4kt < t$ for t > 0. Therefore, we have

Corollary 3.4 (Vats et al, [7]). Suppose that (X,G) is a complete G-metric space and f, a self-map on X satisfying the condition

where 0 < k < 1/4. Then f will have a unique fixed point p.

The final main result of this paper is

Theorem 3.5. Let (X,G) be a complete G-metric space and f be a self-map on X such that

$$G(fx, fy, fz) \le \phi \left(\max \left\{ G(x, fx, fx) + G(x, fy, fy) + G(x, fz, fz), \right. \right.$$

$$G(y, fy, fy) + G(y, fx, fx) + G(y, fz, fz),$$

$$G(z, fz, fz) + G(z, fx, fx) + G(z, fy, fy) \right\} \right)$$

$$(3.27)$$

$$for all x, y, z \in X,$$

where $\phi \in \Phi_5$ is nondecreasing upper semicontinuous. Then f will have a unique fixed point p.

Remark 3.5. Set $\phi(t) = kt$ for all $t \ge 0$, where 0 < k < 1/5 in Theorem 3.5. Then $\phi(0) = 0$ and $\phi(5t) = 5kt < t$ for t > 0. Therefore, we have

Corollary 3.5. Let (X,G) be a complete G-metric space and f be a self-map on X such that

$$G(fx, fy, fz) \le k \max \left\{ G(x, fx, fx) + G(x, fy, fy) + G(x, fz, fz), \right.$$

$$G(y, fy, fy) + G(y, fx, fx) + G(y, fz, fz),$$

$$G(z, fz, fz) + G(z, fx, fx) + G(z, fy, fy) \right\}$$
(3.28)
$$for all \ x, y, z \in X,$$

where $0 \le k < 1/5$. Then f will have a unique fixed point p.

4. G-contractive fixed points

We begin this section with

Definition 4.1 (Phaneendra and Kumara Swamy, [4]). A fixed point p of f on a G-metric space (X,G) is a G-contractive fixed point, if for each $x_0 \in X$, the orbit $O_f(x_0) = \langle x_0, fx_0, ..., f^n x_0, ... \rangle$ is G-convergent, with limit p.

It was shown in [4] that the unique fixed point of the self-map f with the following choices is a G-contractive fixed point.

- (a) $G(fx, fy, fz) \le qG(x, y, z)$ for all $x, y, z \in X$, where $0 \le q < 1$,
- (b) $G(fx, fy, fz) \le aG(x, fx, fx) + bG(y, fy, fy) + cG(z, fz, fz) + eG(x, y, z)$ for all $x, y, z \in X$, where a, b, c and e are nonnegative real numbers with a + b + c + e < 1.

In [5], the authors have proved that the unique fixed points of the self-maps are G-contractive fixed points, under (3.24) and (3.28).

Now, we obtain *G*-contractive fixed points for the maps of Corollaries, obtained in the previous sections.

Theorem 4.1. Let p be a unique fixed point of a self-map f on a complete G-metric space satisfying (3.22). Then p will be a G-contractive fixed point.

Proof. Let $x_0 \in X$ be arbitrary. Writing $x = f^{n-1}x_0$ and y = z = p in (3.22), we get

where

(4.2)
$$\max\{G(f^{n-1}x_0, f^nx_0, f^nx_0), G(f^{n-1}x_0, p, p), G(p, f^nx_0, f^nx_0)\}.$$

Now, three cases arise:

Case (a). Suppose that $M = G(p, f^n x_0, f^n x_0)$. Then, it can be shown that p is a G-contractive fixed point, as in case (a) of the previous proof.

Case (b). The case of $M = G(f^{n-1}x_0, p, p)$ is obvious, since k < 1.

Case (c). Let $M = G(f^{n-1}x_0, f^nx_0, f^nx_0)$. Then, (4.1) can be written as

(4.3)
$$G(f^n x_0, p, p) \le kG(f^{n-1} x_0, f^n x_0, f^n x_0) \text{ for } n \ge 1.$$

But, (3.22) with $x = f^{n-2}x_0$ and $y = z = f^{n-1}x_0$, gives

$$\begin{split} G(f^{n-1}x_0,f^nx_0,f^nx_0) &= G(ff^{n-2}x_0,ff^{n-1}x_0,ff^{n-1}x_0) \\ &\leq k \max \left\{ G(f^{n-2}x_0,f^{n-1}x_0,f^{n-1}x_0), G(f^{n-2}x_0,f^nx_0,f^nx_0), G(f^{n-2}x_0,f^nx_0,f^nx_0), G(f^{n-1}x_0,f^nx_0,f^nx_0), G(f^{n-1}x_0,f^nx_0,f^nx_0,f^nx_0), G(f^{n-1}x_0,f^nx_0,f^nx_0,f^nx_0), G(f^{n-1}x_0,f^nx_0,f^nx_0,f^nx_0), G(f^{n-1}x_0,f^nx_0,f^nx_0,f^nx_0), G(f^{n-1}x_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0), G(f^{n-1}x_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0), G(f^{n-1}x_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0), G(f^{n-1}x_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0,f^nx_0,f^n$$

from which, by induction, it follows that

$$G(f^{n-1}x_0, f^nx_0, f^nx_0) \le \left(\frac{k}{1-k}\right)^{n-1} G(x_0, fx_0, fx_0), n \ge 1.$$

Substituting this in (4.3), we get

(4.4)
$$G(f^{n}x_{0}, p, p) \le k \left(\frac{k}{1-k}\right)^{n-1} G(x_{0}, fx_{0}, fx_{0}) \text{ for } n \ge 1.$$

Applying the limit as $n \to \infty$ in (4.4), we see that $G(f^n x_0, p, p) \to 0$ or $f^n x_0 \to p$ as $n \to \infty$. Since x_0 is arbitrary, we conclude that p is a G-contractive fixed point.

Similarly, we have

Theorem 4.2. Let p be a unique fixed point of a self-map f on a complete G-metric space satisfying (3.20). Then p will be a G-contractive fixed point.

Theorem 4.3. Let p be a unique fixed point of a self-map f on a complete G-metric space satisfying (3.26). Then p will be a G-contractive fixed point.

Proof. Let $x_0 \in X$ be arbitrary. Writing $x = f^{n-1}x_0$ and y = z = p in (3.26) and using (G5), we get

$$G(f^{n}x_{0}, p, p) = G(f^{n}x_{0}, fp, fp)$$

$$\leq k \max \left\{ G(f^{n-1}x_{0}, f^{n}x_{0}, f^{n}x_{0}) + G(f^{n-1}x_{0}, fp, fp) + G(f^{n-1}x_{0}, fp, fp), \right.$$

$$G(p, fp, fp) + G(p, f^{n}x_{0}, f^{n}x_{0}) + G(p, fp, fp),$$

$$G(p, fp, fp) + G(p, f^{n}x_{0}, f^{n}x_{0}) + G(p, fp, fp) \right\}$$

$$= k \max \left\{ G(f^{n-1}x_{0}, f^{n}x_{0}, f^{n}x_{0}) + 2G(f^{n-1}x_{0}, p, p), \right.$$

$$0 + G(p, f^{n}x_{0}, f^{n}x_{0}) + 0, 0 + G(p, f^{n}x_{0}, f^{n}x_{0}) + 0 \right\}$$

$$(4.5) = kM,$$

where

$$(4.6) M = \max\{G(f^{n-1}x_0, f^nx_0, f^nx_0) + 2G(f^{n-1}x_0, p, p), G(p, f^nx_0, f^nx_0)\}.$$

We have two cases:

Case (a). Suppose that $M = G(p, f^n x_0, f^n x_0)$. Then, (4.5), in view of (2.1), can be written as

(4.7)
$$G(f^n x_0, p, p) \le kG(p, f^n x_0, f^n x_0) \le 2kG(p, p, f^n x_0)$$
 for all $n \ge 1$.

If $f^n x_0 \neq p$ for some m, then (4.7) would imply a contradiction that

$$0 < G(p, p, f^m x_0) < G(p, p, f^m x_0),$$

since 2k < 1. Therefore, $f^n x_0 = p$ for all n, so that $f^n x_0 \to p$ as $n \to \infty$. Since x_0 is arbitrary, we conclude that p is a G-contractive fixed point.

Case (b). Let $M = G(f^{n-1}x_0, f^nx_0, f^nx_0) + 2G(f^{n-1}x_0, p, p)$. Then, (4.5) can be written as

(4.8)
$$G(f^n x_0, p, p) \le k[G(f^{n-1} x_0, f^n x_0, f^n x_0) + 2G(f^{n-1} x_0, p, p)], n \ge 1.$$

Now, (3.26) with $x = f^{n-2}x_0$ and $y = z = f^{n-1}x_0$, gives

$$\begin{split} G(f^{n-1}x_0,f^nx_0,f^nx_0) &= G(ff^{n-2}x_0,ff^{n-1}x_0,ff^{n-1}x_0) \\ &\leq k \max \left\{ G(f^{n-2}x_0,f^{n-1}x_0,f^{n-1}x_0) + 2G(f^{n-1}x_0,f^nx_0,f^nx_0), \\ G(f^{n-2}x_0,f^nx_0,f^nx_0) + 0 + G(f^{n-1}x_0,f^nx_0,f^nx_0), \\ G(f^{n-2}x_0,f^nx_0,f^nx_0) + G(f^{n-1}x_0,f^nx_0,f^nx_0) + 0 \right\} \\ &\leq k \max \left\{ G(f^{n-2}x_0,f^{n-1}x_0,f^{n-1}x_0) + 2G(f^{n-1}x_0,f^nx_0,f^nx_0), \\ G(f^{n-2}x_0,f^{n-1}x_0,f^{n-1}x_0) + 2G(f^{n-1}x_0,f^nx_0,f^nx_0) \right\} \\ &= k \left[G(f^{n-2}x_0,f^{n-1}x_0,f^{n-1}x_0) + 2G(f^{n-1}x_0,f^nx_0,f^nx_0) \right] \\ &\leq \left(\frac{k}{1-2k} \right) G(f^{n-2}x_0,f^{n-1}x_0,f^{n-1}x_0), \end{split}$$

from which, by induction, it follows that

$$G(f^{n-1}x_0, f^nx_0, f^nx_0) \le \left(\frac{k}{1-2k}\right)^{n-1} G(x_0, fx_0, fx_0), n \ge 1.$$

Substituting this in (4.8), we get

$$G(f^n x_0, p, p) \le k \left[\left(\frac{k}{1 - 2k} \right)^{n - 1} G(x_0, f x_0, f x_0) + 2G(f^{n - 1} x_0, p, p) \right], n \ge 1,$$

which, again by induction, gives

$$G(f^{n}x_{0}, p, p) \leq k \left[1 + (2k)^{2} + \dots + (2k)^{n-1}\right] \left(\frac{k}{1-2k}\right)^{n-1} G(x_{0}, fx_{0}, fx_{0})$$

$$+ (2k)^{n} G(x_{0}, p, p)$$

$$= k \left[\frac{1 - (2k)^{n}}{1-2k}\right] \left(\frac{k}{1-2k}\right)^{n-1} G(x_{0}, fx_{0}, fx_{0})$$

$$+ (2k)^{n} G(x_{0}, p, p) \text{ for all } n \geq 1.$$

$$(4.9)$$

Note that 2k < 1. Therefore, applying the limit as $n \to \infty$ in (4.9), we see that $G(f^n x_0, p, p) \to 0$ or $f^n x_0 \to p$ as $n \to \infty$. Since x_0 is arbitrary, we conclude that p is a G-contractive fixed point.

Conclusion: A new class Φ_{α} of auxiliary functions has been introduced and then the generalizations of the fixed point theorems of Mustafa and Sims [2], Mohanta [1] and of Vats et al [7] have been proved. Also, *G*-contractive fixed points are obtained for self-maps satisfying the contractive type conditions (3.20), (3.22) and (3.26).

Conflict of Interests

The authors declare that there is no conflict of interests.

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