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A NOTE ON OSCILLATION CRITERIA FOR SOME PERTURBED HALF-LINEAR ELLIPTIC EQUATIONS

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Abstract. In this paper, we show if the half-linear part of an equation is oscillatory, so would be some of its related perturbed equations. For one-dimentional cases, it can be resumed as the following: if the half-linear equation $P(y) := \{a(t)\phi(y')\}' + c(t)\phi(y) = 0$ is oscillatory then any of its perturbed equations P(z) + Q'(t)h(y,y') = 0 will also be oscillatory whenever $Q \in C^1(\mathbb{R})$ and $h \in C(\mathbb{R}^2, \mathbb{R})$.

Keywords: oscillation criteria; half-linear; elliptic equation; solution.

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1. Introduction

This work is somehow an addendum to our earlier result in [4]. For a T > 0, define accordingly $\Omega_T := \{x \in \mathbb{R}^n \mid ||x|| > T, \quad 1 < n \in \mathbb{N}\}$ or $\Omega_T := \{T, \infty) \subset \mathbb{R}$. We investigate some oscillation criteria for equations of the type

$$\begin{cases} (i) & \left\{ a(t)\phi(y') \right\}' + c(t)\phi(y) + g(t)f(y,y') = 0, & t \in \Omega_T \text{ or} \\ (ii) & \nabla \cdot \left\{ A(x)\Phi(\nabla v) \right\} + C(x)\phi(v) + H(x) \cdot F(v,\nabla v) = 0, & x \in \Omega_T, \end{cases}$$

$$(1.1)$$

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where $a, c, g \in C(\Omega_T, \mathbb{R})$; $f \in C(\mathbb{R}^2, \mathbb{R})$; $H \in C(\Omega_T, \mathbb{R}^n)$, $F \in C(\mathbb{R} \times \mathbb{R}^n, \mathbb{R}^n)$; the dot denotes the scalar product in \mathbb{R}^n . For some $\alpha > 0$, $\phi(S) := |S|^{\alpha - 1}S$ for $S \in \mathbb{R}$ and $\Phi(\zeta) := |\zeta|^{\alpha - 1}\zeta$, $\zeta \in \mathbb{R}^n$. They have the following properties: $\forall t, s \in \mathbb{R}$ and $\zeta \in \mathbb{R}^n$

$$\phi(t)\phi(s) = \phi(ts); \quad t\phi'(t) = \alpha\phi(t); \quad t\phi(t) = |t|^{\alpha+1};$$

$$\phi(s)\Phi(\zeta) = \Phi(s\zeta); \quad \zeta\Phi(\zeta) = |\zeta|^{\alpha+1}.$$

Definition 1.1. Let $u \in C(\mathbb{R}, \mathbb{R})$ (or $C(\mathbb{R}^n, \mathbb{R})$).

- (1) A nodal set of u is any open and connected $D(u) \neq \emptyset$ such that $u \neq 0$ in D(u) and $u|_{\partial D(u)} = 0$.
- (2) u is said to be oscillatory (strongly oscillatory) if it has a zero in any Ω_R , R > 0 (in any nodal set $D(u) \subset \Omega_R$).
- (3) An equation will be said to be oscillatory if any of its non-trivial and bounded solutions is oscillatory.

In the sequel the general hypotheses are: for some T, m > 0,

(H1):
$$a \in C^1(\Omega_T, (m, \infty))$$
 is non decreasing: $A \in C^1(\Omega_T, (m, \infty))$; $g \in C(\Omega_T, \mathbb{R})$;

- **(H2)**: $c, C \in C(\Omega_T, (m, \infty))$ eventually; H, f, F are as stated above;
- **(H3)**: On any compact $E \subset \Omega_T$, $\exists k > 0$ such that
- (i) $|g(t)f(S, w)| \le k|w|^{\alpha} + \phi(S)$ if |w| < 1 and S > 0 for the (1.1)(i) case;
- (ii) $|H(x) \cdot F(S, \zeta)| \le k|\zeta|^{\alpha} + \phi(S)$ if $|\zeta| < 1$ and S > 0 for the (1.1)(ii) case.

(The condition (H3) is to ensure that non-trivial solutions are not compact-supported (see [2]).

Oscillation criteria for the equations (1.1)(i) will be obtained through some comparison methods, using some Picone-type identity. Some oscillation criteria for the half-linear equations

(i)
$$\left\{ a(t)\phi(y') \right\}' + c(t)\phi(y) = 0, \quad t \in \Omega_T \quad \text{and}$$

(ii) $\nabla \cdot \left\{ A(x)\Phi(\nabla v) \right\} + C(x)\phi(v) = 0, \quad x \in \Omega_T$

are well known; see *e.g.* [1,3,4] and references therein. For any $w \in C(\mathbb{R}^n, \mathbb{R}^+)$ define $W^+(r) := r^{n-1} \max_{|x|=r} w(x)$ and $W^-(r) := r^{n-1} \min_{|x|=r} w(x)$. The equations in (1.2) are oscillatory if

- (i) a satisfies (H1) and c satisfies (H2) or $t \mapsto \int_T^t c(s)ds$ diverges to infinity for (1.2) (i); (Theorem 1.5 of [3])
 - (ii) $a := A^-$ and $c := C^+$ satisfy the conditions displayed in (i) above for (1.2) (ii). (Theorem 5.1 of [4])

The criteria for (1.2) (ii) are obtained from those of (1.2) (i) using some rightaway transformations and some Picone-type identities; see [1] [3] and the references therein.

2. Picone-type formulae for the equations in (1.1)

If y is a non-trivial C^2 –solution , non zero in some $D \subset \Omega_T$ of (1.1) (i) and z such a solution for (1.2) (i) then

(a) if
$$\exists G \in C^{1}(\Omega_{T}, \mathbb{R})$$
 such that $G'(t) = g(t)$ in Ω_{T} ,
(b) $\left\{ a(t)z\phi(z') - a(t)z\phi(\frac{z}{y}y') - z\phi(\frac{z}{y})G(t)f(y,y') \right\}'$
 $= a(t)\zeta_{\alpha}(z,y) - G(t)\left\{ z\phi(\frac{z}{y})f(y,y') \right\}'$, (2.1)

where, $\forall \gamma > 0$, the two-form function ζ_{γ} is defined $\forall u, v \in C^1(\mathbb{R}, \mathbb{R})$ by

$$(\mathbf{Z1}): \qquad \zeta_{\gamma}(u,v) \left\{ \begin{array}{l} = |u'|^{\gamma+1} - (\gamma+1)u'\phi_{\gamma}(\frac{u}{v}v') + \gamma v'\frac{u}{v}\phi_{\gamma}(\frac{u}{v}v') \\ = |u'|^{\gamma+1} - (\gamma+1)u'\phi_{\gamma}(\frac{u}{v}v') + \gamma |\frac{u}{v}v'|^{\gamma+1} \end{array} \right.$$

is strictly positive for non null $u \neq v$ and is null only if $u = \lambda v$ for some $\lambda \in \mathbb{R}$. Similarly, if $v \in C^2(\Omega_T, \mathbb{R})$ is a non-trivial solution for (1.1) (ii) and u such a solution of (1.2) (ii) then

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wherever $v \neq 0$

(a) if $\exists h \in C^1(\Omega_T, \mathbb{R})$ such that $\nabla h = H(x)$ in Ω_T ,

$$(b) \quad \nabla \cdot \left\{ A(x)u\Phi(\nabla u) - A(x)u\Phi(\frac{u}{v}\nabla v) - u\phi(\frac{u}{v})h(t)F(v,\nabla v) \right\}$$

$$= A(x)Z_{\alpha}(u,v) - h(t)\nabla \cdot \left\{ u\phi(\frac{u}{v})F(v,\nabla v) \right\},$$
where $\forall \gamma > 0, \quad \forall u, v \in C^{1}(\mathbb{R}^{n}).$

$$(2.2)$$

$$(22): \quad Z_{\gamma}(u,v) := |\nabla u|^{\gamma+1} - (\gamma+1)\Phi_{\gamma}(\frac{u}{v}\nabla v) \cdot \nabla u + \gamma|\frac{u}{v}\nabla v|^{\gamma+1}$$

$$= |\nabla u|^{\gamma+1} - (\gamma+1)|\frac{u}{v}\nabla v|^{\gamma-1} \frac{u}{v}\nabla v \cdot \nabla u + \gamma|\frac{u}{v}\nabla v|^{\gamma+1}.$$

We recall that $\forall \gamma > 0$ the two-form $Z_{\gamma}(u, v) > 0$ for distinct non null u, v and is null only if $\exists k \in \mathbb{R}$; u = kv; see [1].

3. Main results

Theorem 3.1. Assume that a, c, g and f satisfy (H1) to (H3). Then

(i)
$$\left\{a(t)\phi(y')\right\}' + c(t)\phi(y) = 0, \ t > T \quad \text{is oscillatory,}$$

(ii) so is $\left\{a(t)\phi(y')\right\}' + c(t)\phi(y) + g(t)f(y,y') = 0, \quad t \in \Omega_T$

provided that $\exists G \in C^1(\Omega_T)$; G'(t) = g(t).

Theorem 3.2. Assume that A, C, F, with $a := A^-, c := C^+$ and H satisfy (H1) to (H3). Then

$$\nabla \cdot \left\{ A(x)\Phi(\nabla v) \right\} + C(x)\phi(v) + H(x) \cdot F(v, \nabla v) = 0, \quad x \in \Omega_T$$
 (3.2)

is oscillatory provided that $\exists h \in C^1(\Omega_T, \mathbb{R}); \quad \nabla h(x) = H(x).$

Since the proofs of the two theorems are similar, we prove only the first one.

Proof of Theorem 3.1. In equation (3.1) (ii) g(t) can be replaced by $G'_{\mu}(t) := [G(t) + \mu]'$, $\forall \mu \in \mathbb{R}$. With that replacement, if y is a non-trivial solution of (3.1)(ii) with y > 0 in

an Ω_R , then for any oscillatory solution z of (3.1) (i), for any nodal set $D(z) \subset \Omega_R$

$$0 = \int_{D(z)} \left[a(t)\zeta_{\alpha}(z, y) \right] dt$$

$$- \int_{D(z)} \left(G(t) + \mu \right) \left\{ z\phi(\frac{z}{y})f(y, y') \right\}' dt \quad \forall \mu \in \mathbb{R}.$$
(3.3)

For $\mu = 0$ we get $0 = \int_{D(z)} \left[a(t) \zeta_{\alpha}(z, y) \right] dt - \int_{D(z)} G(t) \left\{ z \phi(\frac{z}{y}) f(y, y') \right\}' dt$ whence $\mu[z \phi(\frac{z}{y}) f(y, y')] \equiv 0$ and so is $\zeta_{\alpha}(z, y)$ in any such a D(z). Therefore no such a solution y can be non-zero in any Ω_R ; it has to have a zero in any $D(z) \subset \Omega_R$.

Remark 3.3. Following the processes similar to those in the proofs of Theorem 3.4 and Theorem 5.1 of [4], the hypotheses on G and H can be weakened to

$$\exists k \in C(\Omega_T, \mathbb{R}) \text{ and } K \in C(\Omega_T, \mathbb{R}^n)$$

bounded in Ω_T such that the functions G and h above satisfy

$$G'(t) = g(t) + k(t)$$
 and $\nabla h(x) = H(x) + K(x)$. (3.4)

But the penality to pay is that the corresponding solutions y will be oscillatory unless $\liminf_{t \nearrow \infty} |y(t)| = 0$ ($\liminf_{|x| \nearrow \infty} |y(x)| = 0$).

Conflict of Interests

The author declares that there is no conflict of interests.

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