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COMMON FIXED POINT THEOREMS IN COMPLEX VALUED GENERALIZED

METRIC SPACES

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Abstract. In this paper, using (CLR) property and the Common (E.A) property common fixed point results for

weakly compatible mappings, satisfying integral type contractive condition in complex valued generalized metric

spaces are investigated.

Keywords: complex valued generalized metric spaces; weakly compatible mapping; (E.A) property; (CLR) prop-

erty.

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1. Introduction

In 2011, Azam et al. [1] introduced the notion of complex valued metric space which is a

generalization of the classical metric space and proved a unique common fixed point theorems

for two self-mappings satisfying a rational type inequality. Though complex valued metric

spaces form a special class of cone metric space, yet this idea is intended to define rational

expressions which are not meaningful in cone metric spaces and thus many results of analysis

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cannot be generalized to cone metric spaces. However, in complex valued metric spaces, we can study improvements of a host of results of analysis involving division. Bhatt et al. [7] initiated the concept of weakly compatible maps to study common fixed point theorem for weakly compatible maps in complex valued metric spaces.

In 2013, Abbas et al. [2] introduced the notion of complex valued generalized metric space. They replaced the triangular inequality in the complex valued metric by the rectangular inequality involving four points and extended the concept of complex valued metric spaces. They proved fixed point theorems involving the rational type contractive conditions for weakly contractive mappings in these spaces. The fixed point theorems in complex valued generalized metric space were obtained by many mathematicians (e.g. [2,3,8]).

In 2002, Branciari [9] proved fixed point theorems for two self-maps under contractive condition of integral type in metric space. In 2013, Manro et al. [10] extended and generalized the theorem of Branciari [9] for a pair of weakly compatible mappings satisfying a general contractive condition of integral type in complex valued metric space.

The aim of this paper is to prove common fixed point theorems for integral type contractive condition in complex valued generalized metric spaces.

2. Preliminaries

The following definitions and lemmas will be used in the sequel. Let \mathbb{C} be the set of complex numbers and $z_1, z_2 \in \mathbb{C}$. We define a partial order \lesssim on \mathbb{C} as follows: $z_1 \lesssim z_2$, iff $Re(z_1) \leq Re(z_2)$ and $Im(z_1) \leq Im(z_2)$.

As a result, we can say that $z_1 \lesssim z_2$ if one of the following conditions is satisfied:

(I)
$$Re(z_1) = Re(z_2), Im(z_1) < Im(z_2);$$

(II)
$$Re(z_1) < Re(z_2), Im(z_1) = Im(z_2);$$

(III)
$$Re(z_1) < Re(z_2), Im(z_1) < Im(z_2);$$

(IV)
$$Re(z_1) = Re(z_2), Im(z_1) = Im(z_2).$$

In particular, we can write $z_1 \nleq z_2$ if $z_1 \neq z_2$ and one of (I)-(III) is satisfied. Also we will write $z_1 \prec z_2$ if only (III) holds.

We can also prove these results:

(1) $z_1 \lesssim z_2$ and $0 \le r \in R \Longrightarrow rz_1 \lesssim z_2$;

(2)
$$0 \lesssim z_1 \lesssim z_2 \Longrightarrow |z_1| < |z_2|$$
;

(3)
$$z_1 \lesssim z_2$$
 and $z_2 \prec z_3 \Longrightarrow z_1 \prec z_3$.

Definition 2.1. [1] Let X be a nonempty set. If the mapping $d: X \times X \to \mathbb{C}$ satisfies the following axioms:

(i)
$$0 \lesssim d(x,y)$$
, for all $x,y \in X$ and $d(x,y) = 0$ if and only if $x = y$;

(ii)
$$d(x,y) = d(y,x)$$
, for all $x, y \in X$;

(iii)
$$d(x,y) \lesssim d(x,z) + d(z,y)$$
. for all $x,y,z \in X$.

Then d is called a complex valued metric on X and (X,d) is called a complex valued metric space.

Example 2.1. Let $X = \mathbb{C}$, define the mapping $d: X \times X \to \mathbb{C}$ by

$$d(x, y) = 2i|x - y|,$$

where $x, y \in X$. Then (X, d) is a complex valued metric space.

Definition 2.2. [2] Let X be a nonempty set. If the mapping $d: X \times X \to \mathbb{C}$ satisfies the following axioms:

(i)
$$0 \le d(x,y)$$
, for all $x,y \in X$ and $d(x,y) = 0$ if and only if $x = y$;

(ii)
$$d(x,y) = d(y,x)$$
, for all $x, y \in X$;

(iii) $d(x,y) \lesssim d(x,u) + d(u,v) + d(v,y)$, for all $x,y \in X$ and all distinct $u,v \in X$, each one is different from x and y.

Then d is called a complex valued generalized metric on X and (X,d) is called a complex valued generalized metric space.

Example 2.2. Let $X = \{-2, -1, 1, 2\}$ and define the complex valued generalized metric on $d: X \times X \to \mathbb{C}$ as

$$d(-2,2)=d(2,-2)=d(-1,2)=d(2,-1)=d(1,2)=d(2,1)=0.4i$$

$$d(-2,-1) = d(-1,-2) = d(-1,1) = d(1,-1) = 0.2i$$

$$d(-2,1)=d(1,-2)=0.5i$$

$$d(-2,-2) = d(-1,-1) = d(1,1) = d(2,2) = 0$$

We can prove that (X,d) is a complex valued generalized metric space but it is not a complex valued metric space since it does not satisfy triangular inequality, d(-2,1) = 0.5i > d(-2,-1) + d(-1,1) = 0.2i + 0.2i = 0.4i.

Let X be a complex valued generalized metric space and $A \subseteq X$. A point $x \in X$ is called an interior point of a set A whenever there exists $0 \prec r \in \mathbb{C}$ such that $B(x,r) = \{y \in X : d(x,y) \prec r\} \subseteq A$. A subset A in X is called open whenever each point of A is an interior point of A. The family $F = \{B(x,r) : x \in X, 0 \prec r\}$ is a sub-basis for a Hausdorff topology τ on X.

A point $x \in X$ is called a limit point of A whenever for every $0 \prec r \in \mathbb{C}$, $B(x,r) \cap (A \setminus x) \neq \emptyset$. A subset $B \subseteq X$ is called closed whenever each limit point of B belongs to B.

Definition 2.3. [2] Let $\{x_n\}$ be a sequence in complex valued generalized metric space (X,d) and $x \in X$. Then

- (1) x is called the limit of $\{x_n\}$ if for every $\omega \in \mathbb{C}$ with $0 \prec \omega$ there is $n_0 \in N$ such that $d(x_n, x) \prec \omega$ for all $n > n_0$ and we write $\lim_{n \to \infty} x_n = x$.
- (2) $\{x_n\}$ is called a Cauchy sequence if for every $\omega \in \mathbb{C}$ with $0 \prec \omega$ there is $n_0 \in N$ such that $d(x_n, x_m) \prec \omega$ for all $n, m > n_0$.
- (3) (X,d) is said to be a complete complex valued generalized metric space if every Cauchy sequence is convergent in (X,d).

Lemma 2.1. [2] Let (X,d) be a complex valued generalized metric space. Then a sequence $\{x_n\}$ in X converges to x if and only if $|d(x_n,x)| \to 0$ as $n \to \infty$.

Lemma 2.2. [2] Let (X,d) be a complex valued generalized metric space. Then a sequence $\{x_n\}$ in X is a Cauchy sequence if and only if $|d(x_n,x_m)| \to 0$ as $n,m \to \infty$.

Lemma 2.3. $[11]d(x_n, y) \to d(x, y)$ and $d(x, x_n) \to d(x, a)$ whenever $\{x_n\}$ is a sequence in X with $x_n \to x$.

Definition 2.4. [3] Let f and g be two self-mapping on a nonempty set X. Then

- (I) $x \in X$ is called to be fixed point of f if fx = x.
- (II) $x \in X$ is called to be a coincidence point of f and g if fx = gx.
- (III) $x \in X$ is called to be a common fixed point of f and g if fx = gx = x.

Definition 2.5. [3] Let (X,d) be a complex valued generalized metric space. Then two self-mapping f and g are said to be weakly compatible if they commute at their coincidence points, i.e., $x \in X$ with fx = gx implies that fgx = gfx.

Definition 2.6. [4]Let (X,d) be a complex valued generalized metric space. Then two self-mapping f and g are said to satisfy the common limit in the range of g property (CLR_g) if there exists a sequence $\{x_n\}$ in X, $x_n \neq x_m$ if $n \neq m$ such that

$$\lim_{n\to\infty} fx_n = \lim_{n\to\infty} gx_n = gx$$

for some $x \in X$.

Definition 2.7. [5] Let (X,d) be a complex valued generalized metric space. Then two pairs of self maps (S,f) and (T,g) are said to satisfy the Common (E,A) property if there exists two sequence $\{x_n\}$ and $\{y_n\}$ in X $x_n \neq x_m$ and $y_n \neq y_m$ if $n \neq m$ such that

$$\lim_{n\to\infty} Sx_n = \lim_{n\to\infty} fx_n = \lim_{n\to\infty} Ty_n = \lim_{n\to\infty} gy_n = z$$

for some $z \in X$.

3. Main results

In this section, we will prove the existence of fixed points for mappings f and g defined on a complex valued generalized metric space (X,d) satisfying a contractive condition of integral type.

Let $\Phi = \{\phi: \phi: [0,\infty) \to [0,\infty) \text{ is a Lebesgue-integrable mapping which is summable on each compact subset of } [0,\infty), \text{ non-negative, non-decreasing and such that for each } \varepsilon \succ 0, \int_0^\varepsilon \phi(t)dt \succ 0\}.$

For any $z_1, z_2 \in \mathbb{C}_+$, define

$$[z_1, z_2] = \{r(s) \in \mathbb{C} : r(s) = z_1 + s(z_2 - z_1) \text{ for some } s \in [0, 1]\}.$$

 $(z_1, z_2] = \{r(s) \in \mathbb{C} : r(s) = z_1 + s(z_2 - z_1) \text{ for some } s \in [0, 1]\}.$

Define $\zeta:[z_1,z_2]\to\mathbb{C}$ as follow:

$$\zeta(x+iy) = \phi_1(x) + i\phi_2(y),$$

where $x + iy \in [z_1, z_2]$ and $\phi_1, \phi_2 \in \Phi$.

We denote the set of all complex integrable function $\zeta:[z_1,z_2]\to\mathbb{C}$ by $\Gamma^1([z_1,z_2],\mathbb{C})$.

Lemma 3.1. [6] Suppose $\zeta \in \Gamma^1([z_1, z_2], \mathbb{C})$ and $\{z_n\}$ be a sequence in \mathbb{C}_+ , then $\lim_{n\to\infty} \int_0^{z_n} \zeta(s) ds = (0,0)$ if and only if $z_n \to (0,0)$, as $n \to \infty$.

Definition 3.1. [6] A complex valued function $\varphi : \mathbb{R}^n \to \mathbb{C}$ is measurable if both its real and imaginary parts are measurable.

In 2016, Sarwar Muhammad defined the lebesgue integral of f to be

$$\int_{E} f = \int_{E} Re(f) + i \int_{E} Im(f) = \left(\int_{E} Re(f), \int_{E} Im(f) \right),$$

provided that Re(f) and Im(f) are Lebesgue integrables and defined all complex valued lebesgue integrable functions by $\Gamma^1(E,\mathbb{C})$, where $E \subset R^n$ be a measurable set.

We define $\Psi = \{ \varphi : R^n \to \mathbb{C} \text{ as a complex valued Lebesgue-integrable mapping(i.e.,} \varphi \in \Gamma^1(E,\mathbb{C})), \text{ which is summable and non-vanishing on each measurable subset of } R^n, \text{ such that for each } \varepsilon \succ 0, \int_0^\varepsilon \varphi(t)dt \succ 0 \}$

Theorem 3.1. Let f and g be two self-mapping of a complex valued generalized metric space (X,d) which satisfy the following conditions:

- (I) the pairs (f,g) is weakly compatible,
- (II) the pairs (f,g) satisfy (CLR_g) property,
- (III) $\forall x, y \in X$, there exists

$$u(x,y) \in M(x,y)$$

such that

$$\int_{0}^{d(fx,fy)} \varphi(t)dt \prec \alpha \int_{0}^{u(x,y)} \varphi(t)dt \tag{3.1}$$

where α nonnegative real such that $\alpha < 1$ and $\varphi \in \Psi$,

 $M(x,y) = \{d(gx,gy), d(gy,fy), d(gx,fy), d(gy,fx)\}$, then f and g have a unique common fixed point in X.

Proof. Since the mappings f and g satisfy the (CLR_g) property, then there exists sequence $\{x_n\}$ such that

$$\lim_{n\to\infty} fx_n = \lim_{n\to\infty} gx_n = gx,$$

for some $x \in X$. We now show that fx = gx. Suppose not, i.e., $fx \neq gx$.

From (3.1)

$$\int_0^{d(fx_n,fx)} \varphi(t)dt \prec \alpha \int_0^{u(x_n,x)} \varphi(t)dt \tag{3.2}$$

where

$$u(x_n,x) \in M(x_n,x)$$

$$M(x_n, x) = \{d(gx_n, gx), d(gx_n, fx_n), d(gx, fx), d(gx_n, fx), d(gx, fx_n)\}$$

Two cases arises:

1) If

$$u(x_n,x) = d(gx_n,gx), d(gx_n,fx_n) \text{ or } d(gx,fx_n)$$

Taking limit as $n \to \infty$, then (3.2) and lem (3.8) implies

$$\int_0^{d(gx,fx)} \varphi(t)dt < \alpha \int_0^{d(gx,gx)} \varphi(t)dt = 0$$

Which is a contradiction.

2) If

$$u(x_n, x) = d(gx, fx) \text{ or } d(gx_n, fx)$$

Taking limit as $n \to \infty$, then (3.2) and lem (3.8) implies

$$\int_{0}^{d(gx,fx)} \varphi(t)dt \prec \alpha \int_{0}^{d(gx,fx)} \varphi(t)dt$$

Since α < 1, which is a contradiction.

Hence, from all cases, fx = gx. Now let z = fx = gx. Since (f,g) is weakly compatible, fgx = gfx, i.e. fz = gz.

Next we show that fz = z. Suppose it is not, then

$$\int_0^{d(fz,z)} \varphi(t)dt = \int_0^{d(fz,fx)} \varphi(t)dt \prec \alpha \int_0^{u(z,x)} \varphi(t)dt$$
 (3.3)

where

$$u(z,x) \in M(z,x)$$

$$M(z,x) = \{d(gz,gx), d(gz,fz), d(gx,fx), d(gz,fx), d(gx,fz)\}$$

$$= \{d(fz,z), 0, 0, d(fz,z), d(z,fz)\}$$

$$= \{d(fz,z), 0\}$$

Two cases arises:

1) If u(z,x) = d(fz,z), then by (3.3), we have

$$\int_0^{d(fz,z)} \varphi(t)dt \prec \alpha \int_0^{d(fz,z)} \varphi(t)dt$$

Since α < 1, which is a contradiction.

2) If u(z,x) = 0, then by (3.3), we have

$$\int_0^{d(fz,z)} \varphi(t)dt < 0$$

which is a contradiction.

Thus, fz = gz = z.

Hence, z is a common fixed point of f and g.

To show that the fixed point is unique, suppose z' is another fixed point of f and g, i.e. fz' = gz' = z'.

From (3.3), we have

$$\int_0^{d(z,z')} \varphi(t)dt = \int_0^{d(fz,fz')} \varphi(t)dt < \alpha \int_0^{u(z,z')} \varphi(t)dt$$

where

$$u(z,z') \in M(z,z')$$

$$M(z,z') = \{d(gz,gz'), d(gz,fz), d(gz',fz'), d(gz,fz'), d(gz',fz)\}$$

$$= \{d(z,z'),0,0,d(z,z'),d(z',z)\}$$

$$= \{d(z,z'),0\}$$

Two possible cases arises:

1) If u(z,z') = d(z,z'), then by (3.3), we have

$$\int_0^{d(z,z')} \varphi(t)dt \prec \alpha \int_0^{d(z,z')} \varphi(t)dt$$

Since α < 1, which is a contradiction.

2) If u(z, z') = 0, then by (3.46), we have

$$\int_0^{d(z,z')} \varphi(t)dt < 0$$

which is a contradiction.

Hence, z = z' i.e., f and g have a unique common fixed point in X. This completes the proof.

Theorem 3.2. Let S, T, f and g be four self-mapping of a complete complex valued generalized metric space (X,d) which satisfy the following conditions:

- (I) $S(X) \subseteq g(X)$ and $T(X) \subseteq f(X)$,
- (II) the pairs (S, f) and (T, g) are weakly compatible,
- (III) the subspace f(X) or g(X) is closed,
- $(IV) \forall x, y \in X$,

$$\int_{0}^{d(Sx,Ty)} \varphi(t)dt \lesssim (a+c) \int_{0}^{d(fx,gy)} \varphi(t)dt + b \int_{0}^{d(fx,Sx)} \varphi(t)dt + (b+c) \int_{0}^{d(gy,Ty)} \varphi(t)dt$$
 (3.4)

where a, b and c are nonnegative reals such that a+2b+2c<1 and $\phi \in \Psi$, then S, T, f and g have a unique common fixed point in X.

Proof.We construct a sequence $\{y_n\}$ in X such that,

$$y_{2n} = Sx_{2n} = gx_{2n+1}$$

and

$$y_{2n+1} = Tx_{2n+1} = fx_{2n+2}, n \ge 0 (3.5)$$

where $\{x_{2n}\}$ is another sequence in X. Using (3.4), we have,

$$\int_{0}^{d(y_{2n},y_{2n+1})} \varphi(t)dt = \int_{0}^{d(Sx_{2n},Tx_{2n+1})} \varphi(t)dt \lesssim (a+c) \int_{0}^{d(fx_{2n},gx_{2n+1})} \varphi(t)dt
+ b \int_{0}^{d(fx_{2n},Sx_{2n})} \varphi(t)dt + (b+c) \int_{0}^{d(gx_{2n+1},Tx_{2n+1})} \varphi(t)dt
= (a+c) \int_{0}^{d(y_{2n-1},y_{2n})} \varphi(t)dt + b \int_{0}^{d(y_{2n-1},y_{2n})} \varphi(t)dt
+ (b+c) \int_{0}^{d(y_{2n},y_{2n+1})} \varphi(t)dt$$
(3.6)

Hence,

$$\int_{0}^{d(y_{2n},y_{2n+1})} \varphi(t)dt \lesssim \frac{a+b+c}{1-b-c} \int_{0}^{d(y_{2n-1},y_{2n})} \varphi(t)dt$$

Therefore,

$$\int_{0}^{d(y_{2n},y_{2n+1})} \varphi(t)dt \lesssim \delta \int_{0}^{d(y_{2n-1},y_{2n})} \varphi(t)dt$$

where $\delta = \frac{a+b+c}{1-b-c} < 1$, since a+2b+2c < 1. Proceeding in a similar way we have,

$$\int_{0}^{d(y_{2n},y_{2n+1})} \varphi(t)dt \lesssim \delta \int_{0}^{d(y_{2n-1},y_{2n})} \varphi(t)dt$$

$$\lesssim \delta^{2} \int_{0}^{d(y_{2n-2},y_{2n-1})} \varphi(t)dt$$

$$\lesssim \cdots \leq \delta^{2n} \int_{0}^{d(y_{0},y_{1})} \varphi(t)dt$$
(3.7)

Finally we conclude that

$$\int_0^{d(y_n,y_{n+1})} \varphi(t)dt \lesssim \delta^n \int_0^{d(y_0,y_1)} \varphi(t)dt$$

Taking limit as $n \to \infty$, we get

$$\lim_{n \to \infty} \int_0^{d(y_n, y_{n+1})} \varphi(t) dt = 0$$
(3.8)

Hence from lem(3.3), we get $d(y_n, y_{n+1}) \to 0$, as $n \to \infty$.

We now show that $\{y_n\}$ is Cauchy. Suppose that it is not. Then there exists an $\varepsilon > 0$ and subsequences $\{2m\}$ and $\{2n\}$ such that $2n > 2m > n_0$ with

$$d(y_{2m}, y_{2n}) \succeq \varepsilon, d(y_{2m}, y_{2n-1}) \prec \varepsilon \tag{3.9}$$

Now from rectangular inequality,

$$d(y_{2m-1}, y_{2n-1}) \lesssim d(y_{2m-1}, y_{2m}) + d(y_{2m}, y_{2n-2}) + d(y_{2n-2}, y_{2n-1})$$
(3.10)

Therefore, from (3.7), (3.9) and (3.10), we have,

$$\int_{0}^{\varepsilon} \varphi(t)dt \lesssim \int_{0}^{d(y_{2m},y_{2n})} \varphi(t)dt \lesssim \delta \int_{0}^{d(y_{2m-1},y_{2n-1})} \varphi(t)dt$$
$$\lesssim \delta \int_{0}^{d(y_{2m-1},y_{2m})} \varphi(t)dt + \delta \int_{0}^{d(y_{2m},y_{2n-2})} \varphi(t)dt$$
$$+ \delta \int_{0}^{d(y_{2n-2},y_{2n-1})} \varphi(t)dt \prec \delta \int_{0}^{\varepsilon} \varphi(t)dt$$
$$+ \delta \int_{0}^{d(y_{2m-1},y_{2m})} \varphi(t)dt + \delta \int_{0}^{d(y_{2n-2},y_{2n-1})} \varphi(t)dt$$

Taking the limit as $n, m \to \infty$, from (3.8) we have,

$$\int_0^{\varepsilon} \varphi(t)dt \prec \delta \int_0^{\varepsilon} \varphi(t)dt$$

which is a contraction. Therefore $\{y_n\}$ is Cauchy sequence in X. Since X is complete, there exists point z in X such that,

$$\lim_{n \to \infty} Sx_{2n} = \lim_{n \to \infty} gx_{2n+1} = \lim_{n \to \infty} Tx_{2n+1} = \lim_{n \to \infty} fx_{2n+2} = z$$

Assuming f(X) is closed, $z \in f(X)$ and z = fu for some $u \in X$. We claim that Su = fu = z. Using the rectangular inequality[Definition 2.2(iii)] we get,

$$d(Su,z) \lesssim d(Su,Tx_{2n+1}) + d(Tx_{2n+1},gx_{2n+1}) + d(gx_{2n+1},z)$$
(3.11)

Therefore from (3.11),

$$\int_{0}^{d(Su,z)} \varphi(t)dt \lesssim \int_{0}^{d(Su,Tx_{2n+1})} \varphi(t)dt + \int_{0}^{d(Tx_{2n+1},gx_{2n+1})} \varphi(t)dt + \int_{0}^{d(gx_{2n+1},z)} \varphi(t)dt$$

$$\lesssim (a+c) \int_{0}^{d(fu,gx_{2n+1})} \varphi(t)dt + (b+c) \int_{0}^{d(gx_{2n+1},Tx_{2n+1})} \varphi(t)dt$$

$$+ b \int_{0}^{d(fu,Su)} \varphi(t)dt + \int_{0}^{d(Tx_{2n+1},gx_{2n+1})} \varphi(t)dt + \int_{0}^{d(gx_{2n+1},z)} \varphi(t)dt$$

As $n \to \infty$, we get,

$$\int_0^{d(Su,z)} \varphi(t)dt \lesssim (a+c) \int_0^{d(z,z)} \varphi(t)dt + (b+c) \int_0^{d(z,z)} \varphi(t)dt$$
$$+ b \int_0^{d(z,Su)} \varphi(t)dt + \int_0^{d(z,z)} \varphi(t)dt + \int_0^{d(z,z)} \varphi(t)dt$$
$$= b \int_0^{d(z,Su)} \varphi(t)dt$$

As b < 1, $\int_0^{d(z,Su)} \varphi(t) dt = 0$ implies that Su = z i.e. fu = Su = z and u is a coincidence point of f and S. Since $S(X) \subseteq g(X)$, Su = gv for some $v \in X$. Hence fu = Su = gv = z. We claim that Tv = z. By the inequality (3.4),

$$\int_{0}^{d(z,Tv)} \varphi(t)dt = \int_{0}^{d(Su,Tv)} \varphi(t)dt \lesssim (a+c) \int_{0}^{d(fu,gv)} \varphi(t)dt + b \int_{0}^{d(fu,Su)} \varphi(t)dt + (b+c) \int_{0}^{d(gv,Tv)} \varphi(t)dt = (a+b+c) \int_{0}^{d(z,z)} \varphi(t)dt + (b+c) \int_{0}^{d(z,Tv)} \varphi(t)dt = (b+c) \int_{0}^{d(z,Tv)} \varphi(t)dt$$

Since $b+c < 1, \int_0^{d(z,Tv)} \varphi(t) dt = 0$ implies that Tv = z, hence Su = fu = Tv = gv = z. As S and f are weakly compatible, Sfu = fSu i.e. Sz = fz. We now prove that Sz = z, suppose not,

 $Sz \neq z$, then by (3.4),

$$\int_{0}^{d(Sz,z)} \varphi(t)dt = \int_{0}^{d(Sz,Tv)} \varphi(t)dt \lesssim (a+c) \int_{0}^{d(fz,gv)} \varphi(t)dt + b \int_{0}^{d(fz,Sz)} \varphi(t)dt + (b+c) \int_{0}^{d(gv,Tv)} \varphi(t)dt = (a+2c) \int_{0}^{d(Sz,z)} \varphi(t)dt + b \int_{0}^{d(fz,Sz)} \varphi(t)dt + (b+c) \int_{0}^{d(z,z)} \varphi(t)dt = (a+2c) \int_{0}^{d(Sz,z)} \varphi(t)dt$$

Since a + 2c < 1, $\int_0^{d(Sz,z)} \varphi(t)dt$ implies that Sz = z i.e. Sz = fz = z. Thus z is a fixed point of S and f. Also since T and g are weakly compatible, Tgv = gTv i.e. Tz = gz. We now prove that Tz = z, suppose not, $Tz \neq z$, then by (3.4) again,

$$\int_{0}^{d(z,Tz)} \varphi(t)dt = \int_{0}^{d(Sz,Tz)} \varphi(t)dt \lesssim (a+c) \int_{0}^{d(fz,gz)} \varphi(t)dt + b \int_{0}^{d(fz,Sz)} \varphi(t)dt + b$$

Since a + c < 1, $\int_0^{d(Tz,z)} \varphi(t) dt$ implies that Tz = z and Sz = fz = Tz = gz = z, z is a common fixed point of S, T, f and g. To show that the fixed point is unique, suppose that there is another point $w \in X$ such that Sw = Tw = fw = gw = w.

From (3.4), we have,

$$\int_{0}^{d(w,z)} \varphi(t)dt = \int_{0}^{d(Sw,Tz)} \varphi(t)dt \lesssim (a+c) \int_{0}^{d(fw,gz)} \varphi(t)dt + b \int_{0}^{d(fw,Sw)} \varphi(t)dt + (b+c) \int_{0}^{d(gz,Tz)} \varphi(t)dt = (a+c) \int_{0}^{d(w,z)} \varphi(t)dt + b \int_{0}^{d(w,w)} \varphi(t)dt + (b+c) \int_{0}^{d(z,z)} \varphi(t)dt = (a+c) \int_{0}^{d(w,z)} \varphi(t)dt$$

Therefore $\int_0^{d(w,z)} \varphi(t)dt = 0$ as a + c < 1 and w = z which proves the uniqueness of the fixed point. Similar argument holds if g(X) is assumed to be closed. Hence S, T, f and g have a unique common fixed point in X. This completes the proof.

By putting c = 0, in Theorem 3.2 above, we get the following corollary.

Corollary 3.3. Let S, T, f and g be four self-mapping of a complete complex valued generalized metric space (X,d) which satisfy the following conditions:

(I)
$$S(X) \subseteq g(X)$$
 and $T(X) \subseteq f(X)$,

- (II) the pairs (S, f) and (T, g) are weakly compatible,
- (III) the subspace f(X) or g(X) is closed,
- (*IV*) $\forall x, y \in X$,

$$\int_0^{d(Sx,Ty)} \varphi(t)dt \lesssim a \int_0^{d(fx,gy)} \varphi(t)dt + b \left(\int_0^{d(fx,Sx)} \varphi(t)dt + \int_0^{d(gy,Ty)} \varphi(t)dt\right)$$

where a and b are nonnegative reals such that a+2b < 1 and $\phi \in \Psi$, then S, T, f and g have a unique common fixed point in X.

If we put T = S and g = f, b = c = 0 in Theorem 3.2 above, we get the following corollary.

Corollary 3.4. Let S and f be two mappings of a complete complex valued generalized metric space (X,d) which satisfy the following conditions:

- (I) $S(X) \subseteq f(X)$,
- (II) the pair (S, f) is weakly compatible,
- (III) the subspace f(X) is closed,
- (*IV*) $\forall x, y \in X$,

$$\int_{0}^{d(Sx,Ty)} \varphi(t)dt \lesssim a \int_{0}^{d(fx,gy)} \varphi(t)dt$$

where a is nonnegative real such that a < 1 and $\phi \in \Psi$, then S and f have a unique common fixed point in X.

Theorem 3.5. Let S,T,f and g be four self-mapping of a complex valued generalized metric space (X,d) which satisfy the following condition:

- (I) the pairs (S, f) and (T, g) are weakly compatible;
- (II) the pairs (S, f) and (T, g) satisfy the Common property (E, A);
- (III) the subspaces f(X) and g(X) are closed;
- (*IV*) $\forall x, y \in X$,

$$\int_{0}^{d(Sx,Ty)} \varphi(t)dt \lesssim a \int_{0}^{d(fx,gy)} \varphi(t)dt + b \left(\int_{0}^{d(fx,Sx)} \varphi(t)dt + \int_{0}^{d(gy,Ty)} \varphi(t)dt \right) + c \left(\int_{0}^{d(fx,Ty)} \varphi(t)dt + \int_{0}^{d(gy,Sx)} \varphi(t)dt \right)$$
(3.12)

where a, b and c are nonnegative reals such that a+2b+2c<1 and $\phi \in \Psi$, then S, T, f and g have a unique common fixed point in X.

Proof. Since the pairs (S, f) and (T, g) satisfy the common property (E, A), there exists two sequences $\{x_n\}$ and $\{y_n\}$ in X such that

$$\lim_{n \to \infty} Sx_n = \lim_{n \to \infty} fx_n = \lim_{n \to \infty} Ty_n = \lim_{n \to \infty} gy_n = z$$

for some $z \in X$. Since f(X) is closed and $z \in f(X)$, there exists $u \in X$ such that z = fu. We claim that Su = fu = z. From (3.12) we have,

$$\int_0^{d(Su,Ty_n)} \varphi(t)dt \lesssim a \int_0^{d(fu,gy_n)} \varphi(t)dt + b \left(\int_0^{d(fu,Su)} \varphi(t)dt + \int_0^{d(gy_n,Ty_n)} \varphi(t)dt \right) + c \left(\int_0^{d(fu,Ty_n)} \varphi(t)dt + \int_0^{d(gy_n,Su)} \varphi(t)dt \right)$$

As $n \to \infty$,

$$\int_0^{d(Su,z)} \varphi(t)dt \lesssim b \int_0^{d(fu,Su)} \varphi(t)dt + c \int_0^{d(z,Su)} \varphi(t)dt$$

As b+c < 1, d(Su,z) = 0 and Su = z i.e. Su = fu = z. Since S and f are weakly compatible, Sfu = fSu and Sz = fz i.e. z is a coincidence point of S and f. Also since g(X) is closed and $z \in g(X)$, z = gv for some $v \in X$. Hence Su = fu = gv = z. We prove that Tv = gv = z. Consider from (3.12),

$$\int_0^{d(z,Tv)} \varphi(t)dt = \int_0^{d(Su,Tv)} \varphi(t)dt \lesssim a \int_0^{d(fu,gv)} \varphi(t)dt$$
$$+b(\int_0^{d(fu,Su)} \varphi(t)dt + \int_0^{d(gv,Tv)} \varphi(t)dt)$$
$$+c(\int_0^{d(fu,Tv)} \varphi(t)dt + \int_0^{d(gv,Su)} \varphi(t)dt$$
$$= (b+c) \int_0^{d(z,Tv)} \varphi(t)dt$$

Hence d(z, Tv) = 0 as b + c < 1. Therefore Tv = gv = z. Since T and g are weakly compatible, we have Tgv = gTv i.e. Tz = gz and z is a coincidence point of T and g. To show that z is a fixed point, we claim that Sz = z. By (3.12),

$$\int_0^{d(Sz,z)} \varphi(t)dt = \int_0^{d(Sz,Tv)} \varphi(t)dt \lesssim a \int_0^{d(fz,gv)} \varphi(t)dt$$
$$+b(\int_0^{d(fz,Sz)} \varphi(t)dt + \int_0^{d(gv,Tv)} \varphi(t)dt)$$
$$+c(\int_0^{d(fz,Tv)} \varphi(t)dt + \int_0^{d(gv,Sz)} \varphi(t)dt$$
$$= (a+2c) \int_0^{d(z,Sz)} \varphi(t)dt$$

Since a + 2c < 1, d(Sz, z) = 0 and Sz = z. Hence Sz = fz = z. Similarly we can show that Tz = gz = z. Thus we have Sz = fz = Tz = gz = z and z is a common fixed point of S, T, f and g in X.

Uniqueness. let z' be another fixed point of S,T, f and g, i.e. Sz' = Tz' = fz' = gz' = z'. From (3.12), we have

$$\int_0^{d(z,z')} \varphi(t)dt = \int_0^{d(Sz,Tz')} \varphi(t)dt \lesssim a \int_0^{d(fz,gz')} \varphi(t)dt$$

$$+ b \left(\int_0^{d(fz,Sz)} \varphi(t)dt + \int_0^{d(gz',Tz')} \varphi(t)dt \right)$$

$$+ c \left(\int_0^{d(fz,Tz')} \varphi(t)dt + \int_0^{d(gz',Sz)} \varphi(t)dt \right)$$

$$= (a+2c) \int_0^{d(z,z')} \varphi(t)dt$$

thus

$$(1-a-2c)\int_0^{d(z,z')} \varphi(t)dt \lesssim 0$$

Since 1 - a - 2c > 0, which is a contradiction, unless z = z'. Hence z is a unique common fixed point of S, T, f and g in X. This completes the proof.

Conflict of Interests

The authors declare that there is no conflict of interests.

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