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COMMON FIXED POINT THEOREM FOR TWO SELFMAPS OF A G-METRIC **SPACE**

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Abstract. In this paper, we prove a common fixed point theorem for two compatible self maps of a G-metric space.

Keywords: G-metric space; compatible mappings; fixed point; associated sequence of a point relative to two self

maps; contractive modulus.

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1. Introduction

commuting mappings were generalized as weakly commuting maps by Sessa[8]. Later

G.Jungck[4, 5] introduced compatibility as a further generalization of weakly commuting maps.

Among all generalizations [1,2,3,9] of metric spaces, G-metric spaces initiated by Zead Mustafa

and Brailey Sims[6, 7] evinced interest in many researchers.

in the present paper we prove a common fixed point theorem for two compatible self maps of a

G -metric space.

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2. Preliminaries

Before proving the main result we begin with,

Definition 2.1: Let *X* be a non empty set and

 $G: X^3 \to [0, \infty)$ be a function satisfying

(G1)
$$G(x, y, z) = 0$$
 if $x = y = z$

(G2)
$$0 < G(x,x,y)$$
 for all $x,y \in X$ with $x \neq y$

(G3)
$$G(x,x,y) \le G(x,y,z)$$
 for all $x,y,z \in X$ with $z \ne y$

(G4) $G(x,y,z) = G(\sigma(x,y,z))$ for all $x,y,z \in X$ where $\sigma(x,y,z)$ is a permutation of the set $\{x,y,z\}$ and

(G5)
$$G(x, y, z) \le G(x, w, w) + G(w, y, z)$$
 for all $x, y, z, w \in X$

Then G is called a G-metric on X and the pair (X,G) is called a G-metric space.

Definition 2.2: Let (X,G) be a G-metric Space. A sequence $\{x_n\}$ in X is said to be G-convergent if there is a $x_0 \in X$ such that to each $\varepsilon > 0$ there is a natural number N for which $G(x_n, x_n, x_0) < \varepsilon$ for all n > N.

Definition 2.3: Let (X,G) be a G-metric Space. A sequence $\{x_n\}$ in X is said to be G-Cauchy if for each $\varepsilon > 0$ there exists is a natural number N such that $G(x_n, x_m, x_l) < \varepsilon$ for all $n, m, l \ge N$. Note that every G-convergent sequence in a G-metric space (X,G) is G-Cauchy.

Definition 2.4: Let f and g be two self maps of a G-metric space (X, G) such that $\lim_{n\to\infty} G(fgx_n, gfx_n, gfx_n) = 0$ for every sequence $\{x_n\}$ in X with $\lim_{n\to\infty} fx_n = \lim_{n\to\infty} gx_n = t$ for some $t \in X$, then the functions f and g are said to be compatible.

Definition 2.5: A function $\psi : [0, \infty) \to [0, \infty)$ is said to be a contractive modulus if $\psi(0) = 0$ and $\psi(t) < t$ for t > 0

Definition 2.6: Let f and g be self maps of a non-empty set X and let $x_0 \in X$, we can find a sequence $\{x_n\}$ in X satisfying that $fx_n = gx_{n-1}$ for $n \ge 0$ then $\{x_n\}$ is called an associated sequence of x_0 relative to the self maps f and g.

3. Main Result

Theorem 3.1: Suppose f is continuous selfmap of a G-metric space (X,G), then f has a fixed point in X if and only if there is a contractive modulus ψ and a continuous selfmap g of X such that:

- (i) f and g are compatible
- (ii) $G(gx, gy, gy) \le \psi(G(fx, fy, fy))$ for all $x, y \in X$ and
- (iii) there is a point $x_0 \in X$ and an associated sequence $\{x_n\}$ of x_0 relative to the selfmaps f and g such that the sequence $\{fx_n\}$ converges to some point t of X.

Further gt is the unique common fixed point of f and g.

Proof: To prove the necessary part, suppose that f has a fixed point, say 'a', $a \in X$, then fa = a. Define $g: X \to X$ by gx = a for all $x \in X$. Now for any $x \in X$, we have (gf)x = g(fx) = a and (fg)x = fgx = fa = a for any $x \in X$, giving that fg = gf, so that f and g are compatible. Now let ψ be a contractive modulus, then $\psi(0) = 0$ and $\psi(t) < t$ for t > 0 and for any $x, y \in X$ $G(gx, gy, gy) = G(a, a, a) = 0 \le \psi(G(fx, fy, fy))$.

Further an associated sequence of $x_0 = a$ relative to the selfmaps f and g is given by $x_n = a$ for $n = 0, 1, 2, 3 \cdots$, and since the sequence $\{fx_n\}$ is a constant sequence converging to a, which is a point in X.

Thus the conditions (i) (ii) and (iii) of the theorem are satisfied.

Conversely, suppose that there is a contractive modulus ψ and a selfmap g of X satisfying (i) (ii) and (iii) of the theorem hold.

From the condition (iii) of the theorem there is an associated sequence $\{x_n\}$ of x_0 relative to the selfmaps f and g such that $fx_n = gx_{n-1}$ for $n = 1, 2, 3 \cdots$ and $fx_n \to t$ as $n \to \infty$ for some $t \in X$. Then since $gx_n = fx_{n+1}$, it follows that $gx_n \to t$ as $n \to \infty$.

Now we show that g is continuous on X. To see this, suppose that $\{y_n\}$ is a sequence in X with $y_n \to y$ as $n \to \infty$, $y \in X$. Since f is continuous $fy_n \to fy$ as $n \to \infty$, this together with inequality (ii) of the theorem, we get $G(gy_n, gy, gy) \le \psi(G(fy_n, fy, fy)) \to 0$ as $n \to \infty$, which implies that $gy_n \to gy$ as $n \to \infty$, showing that g is continuous.

Using the continuity of f and g,we get $gfx_n \to gt, fgx_n \to ft$ as $n \to \infty$. Since $fx_n \to t, gx_n \to t$

as $n \to \infty$ and f and g are compatible, we have $\lim_{n \to \infty} G(fgx_n, gfx_n, gfx_n) = 0$ which implies that G(ft, gt, gt) = 0 gives ft = gt. To show that fgt = gft, take $z_n = t$ for $n = 1, 2, 3 \cdots$ so that $fz_n \to ft$ and $gz_n \to gt$ as $n \to \infty$. Since ft = gt, f and g are compatible, we get $\lim_{n \to \infty} G(fgz_n, gfz_n, gfz_n) = 0$.

Using the continuity of G, f and g, we get $gfz_n \to gft$ and $fgz_n \to fgt$ as $n \to \infty$. It follows that G(fgt, gft, gft) = 0 and hence fgt = gft

Consequently

$$(1) fft = fgt = gft = ggt$$

If possible suppose that $gt \neq ggt$, then G(gt, ggt, ggt) > 0 and hence

(2)
$$\psi(G(gt, ggt, ggt)) < G(gt, ggt, ggt)$$

But from (ii) of the theorem and 1 we get

$$G(gt,ggt,ggt) \leq \psi(G(ft,fgt,fgt)) = \psi(G(gt,ggt,ggt))$$

which is contradicts to 2, hence gt = ggt.

Using this in 1 we get ggt = gt = fgt, showing that gt is a common fixed point of f and g.

Uniqueness: Suppose that u = fu = gu and v = fv = gv for some $u, v \in X$.

if possible suppose that $u \neq v$, then $G(u, v, v) \neq 0$ so that

$$(3) \qquad \qquad \psi(G(u,v,v)) < G(u,v,v)$$

from (ii) of the theorem we have

$$G(u,v,v) = G(gu,gv,gv) \le \psi(G(fu,fv,fv)) = \psi(G(u,v,v))$$

which is contradiction to 3, hence u = v, proving the theorem.

Corollary 3.2: Suppose f is continuous selfmap of a G-metric space (X, G), then f has a fixed point in X if and only if there is a contractive modulus ψ and a selfmap g of X such that

(i)
$$fg = gf$$

(ii)
$$G(gx, gy, gy) \le \psi(G(fx, fy, fy))$$
 for all $x, y \in X$ and

(iii) there is a point $x_0 \in X$ and an associated sequence $\{x_n\}$ of x_0 relative to the selfmaps f and g such that the sequence $\{fx_n\}$ converges to some point t of X. Further gt is the unique common fixed point of f and g.

Proof: From the fact that the commutativity implies the compatibility of a pair of selfmaps proof of the corollary follows from the Theorem 3.

Corollary 3.3: Suppose f and g are selfmaps of a G-metric space (X,G). Let f is continuous and if there is a contractive modulus ψ and a positive integer k such that:

- (i) fg = gf
- (ii) $G(g^k x, g^k y, g^k y) \le \psi(G(fx, fy, fy))$ for all $x, y \in X$ and
- (iii) there is a point $x_0 \in X$ and an associated sequence $\{x_n\}$ of x_0 relative to the selfmaps f and g^k such that the sequence $\{fx_n\}$ converges to some point t of X. Further gt is the unique common fixed point of f and g.

Proof: From the condition (i) of the corollary 3 we get $fg^k = g^k f$. Thus f and g^k are commuting and hence satisfying the hypothesis of 3, and therefore f and g^k have a unique common fixed point say b, then $g^k b = b = fb$.

Now
$$g^k gb = g^{k+1}b = gg^k b = gb$$
 and $fgb = gfb = gb$.

This shows that gb is a common fixed point of f and g^k . The uniqueness of b implies that gb = b since fb = b, b is a common fixed point of f and g.

To prove that f and g have unique common fixed point, suppose that u = fu = gu and v = fv = gv for some $u, v \in X$, so that $g^k u = u$ and $g^k v = v$, this shows that u, v are common fixed points of f and g^k . The uniqueness of common fixed point of f and g^k implies u = v.

Corollary 3.4: Let p be a positive integer. If g is continuous selfmap of a G-metric space (X,G), such that:

- (i) $G(fx, fy, fy) \le \psi(G(g^Px, g^Py, g^Py))$ for all $x, y \in X$ and
- (ii) there is a point $x_0 \in X$ and an associated sequence $\{x_n\}$ of x_0 relative to the selfmaps g^p and I(where I is the identity map on X) such that the sequence $\{g^px_n\}$ converges to some point t of X. Then g has a unique common fixed point in X.

Proof: We know that $g^p I = Ig^p$. From (ii) of the corollary 3, we have

$$G(x, y, y) = G(Ix, Iy, Iy) \le \psi G(g^p x, g^p y, g^p y)$$
 for all $x, y \in X$.

Since g is continuous, g^p is continuous. Applying corollary 5.3.1 to the function g^p and I, we have unique common fixed point, showing that g has unique fixed point as every point of X is a fixed point of I.

CONFLICT OF INTERESTS

The author(s) declare that there is no conflict of interests.

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